

HCI/ComS 575X: Computational Perception

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# Lecture Plan

- HW3: Due tonight
- Project Updates
- Face Detection: Neural Networks Approach
- Face Detection: Cascades
- OpenCV Demo

Face Detection v.s. Face Recognition

Henry A. Rowley, Shumeet Baluja and Takeo Kanade (1997).

> "Rotation Invariant Neural Network-Based Face Detection," Carnegie Mellon Technical Report, CMU-CS-97-201.

# Rotation Invariant Face Detection

















# Testing on Images with no Faces All detections are automatically false positives They are added as negative examples in the training database

	Upright Test Set		Rotated Test Set	
System	Detect %	# False	Detect %	# False
Network 1	89.6%	4835	91.5%	2174
Network 2	87.5%	4111	90.6%	1842
Net $1 \rightarrow Postproc$	85.7%	2024	89.2%	854
Net $2 \rightarrow Postproc$	84.1%	1728	87.0%	74:
$Postproc \to AND$	81.6%	293	85.7%	119





**Face Detection Movies** 

# Web Demo of Face Detection

http://demo.pittpatt.com/

Face Detection Using Cascades

Paul Viola and Michael Jones (2001).

"Robust Real-time Object Detection", Second International Workshop on Statistical and Computational Theories of Vision Modeling, Learning, Computing, and Sampling, Vancouver, Canada, July 13, 2001.



# Viola/Jones Face Detector

- Technical advantages:
  - Uses lots of very simple box features, enabling an efficient image representation
  - Scales features rather than source image
  - Cascaded classifier is very fast on non-faces
- Practical benefits:
  - Very fast, compact footprint
  - You don't have to implement it!
  - (should be in latest version of OpenCV)

# This next set of slides is from:

# Robust Real-time Object Detection

by Paul Viola and Michael Jones ICCV 2001 Workshop on Statistical and Computation Theories of Vision

> Presentation by Gyozo Gidofalvi Computer Science and Engineering Department University of California, San Diego gyozo@cs.ucsd.edu October 25, 2001

## Object detection task

- Object detection framework: Given a set of images find regions in these images which contain instances of a certain kind of object.
- Task: Develop an algorithm to learn an fast and accurate method for object detection.

To capture ad-hoc domain knowledge classifiers for images do not operate on raw grayscale pixel values but rather on values obtained from applying simple filters to the pixels.

# Definition of simple features for object detection



 3 rectangular features types:
 two-rectangle feature type (horizontal/vertical)
 three-rectangle feature type

• four-rectangle feature type

Using a 24x24 pixel base detection window, with all the possible combination of horizontal and vertical location and scale of these feature types the full set of features has 49,396 features.

The motivation behind using rectangular features, as opposed to more expressive steerable filters is due to their extreme computational efficiency.







# Challenges for learning a classification function

- Given a feature set and labeled training set of images one can apply number of machine learning techniques.
- Recall however, that there is 45,396 features associated with each image sub-window, hence the computation of all features is computationally prohibitive.
- Hypothesis: A combination of only a small number of these features can yield an effective classifier.
- · Challenge: Find these discriminant features.



### Speed-up through the Attentional Cascade

• Simple, boosted classifiers can reject many of negative subwindows while detecting all positive instances.

• Series of such simple classifiers can achieve good detection performance while eliminating the need for further processing of negative sub-windows.



### Processing in / training of the Attentional Cascade

**Processing**: is essentially identical to the processing performed by a degenerate decision tree, namely only a positive result from a previous classifier triggers the evaluation of the subsequent classifier.

Training: is also much like the training of a decision tree, namely subsequent classifiers are trained only on examples which pass through all the previous classifiers. Hence the task faced by classifiers further down the cascade is more difficult.

To achieve efficient cascade for a given false positive rate F and detection rate D we would like to minimize the expected number of features evaluated N:

# $N = n_0 + \sum_{i=1}^{K} \left( n_i \prod_{j < i} p_j \right)$

Since this optimization is extremely difficult the usual framework is to choose a minimal acceptable false positive and detection rate per layer.

# Experiments (dataset for training)

- 4916 positive training example were hand picked aligned, normalized, and scaled to a base resolution of 24x24
- 10,000 negative examples were selected by randomly picking sub-windows from 9500 images which did not contain faces



# Experiments cont. (structure of the detector cascade)

The final detector had 32 layers and 4297 features total

Layer number	1	2	3 to 5	6 and 7	8 to 12	13 to 32
Number of feautures	2	5	20	50	100	200
Detection rate	100%	100%	-	-	-	
Rejection rate	60%	80%	-	-	-	-

Speed of the detector ~ total number of features evaluated
On the MIT-CMU test set the average number of features evaluated is

8 (out of 4297). • The processing time of a 384 by 288 pixel image on a conventional

personal computer about .067 seconds. • Processing time should linearly scale with image size, hence

 Processing time should linearly scale with image size, nence processing of a 3.1 mega pixel images taken from a digital camera should approximately take 2 seconds.

# <text><text><list-item>





Live OpenCV Demo of Face Detection Using Cascades

THE END