CprE 281:
Digital Logic

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http://www.ece.iastate.edu/~alexs/classes/

Algorithmic State Machine (ASM) Charts

Administrative Stuff

- **Homework 12 is out**

- **It is due on Wednesday November 30 @ 10pm**

- **Final Project Proposals**
  - **Did you hear back from your TAs?**
  - **Did you make the changes that they recommended?**

Administrative Stuff

- **Extra credit lab is due on December 2 @ 10 pm**

Administrative Stuff

- **Final Project: due during your last lab (dead week).**

  - The grading rubric is posted on the class web page.

  - presentation of your work to your TAs

  - final report pdf (upload on canvas)

  - zip file with your design (upload on canvas)

  - If you work in a team: each student needs to present separately to their lab TAs.

Administrative Stuff

- **The FINAL exam is scheduled for**

   Wednesday Dec 14 @ 2:15 – 4:15 PM
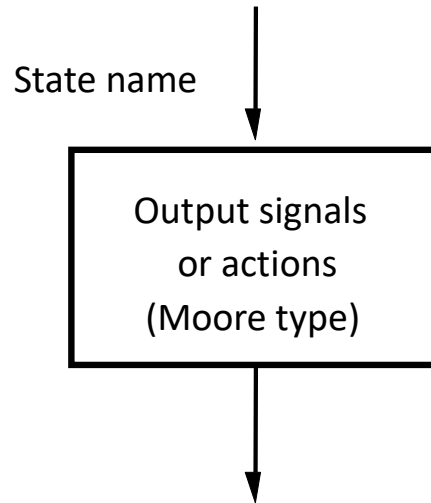
Reading Material for Next Lecture

- "The Seven Secrets of Computer Power Revealed" by Daniel Dennett.

- This is Chapter 24 in his book
  "Intuition Pumps and Other Tools for Thinking", 2013

Algorithmic State Machine (ASM) Charts

Elements used in ASM charts

State name

Output signals
or actions
(Moore type)

(a) State box

0 (False)   Condition
expression   1 (True)

(b) Decision box

Conditional outputs
or actions (Mealy type)

(c) Conditional output box

[Figure 6.81 from the textbook]

State Box

State name

Output signals
or actions
(Moore type)

[Figure 6.81a from the textbook]
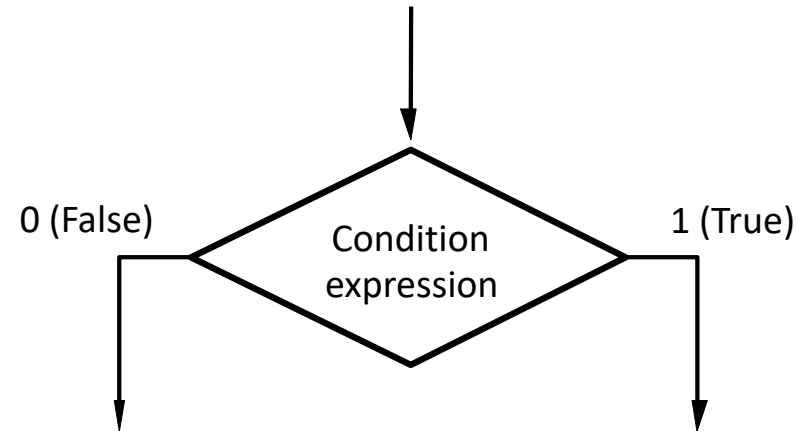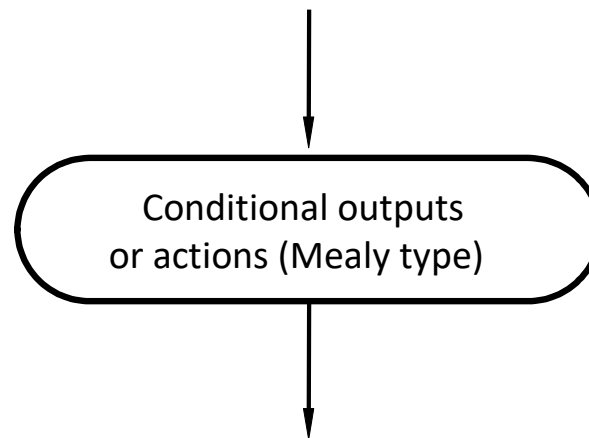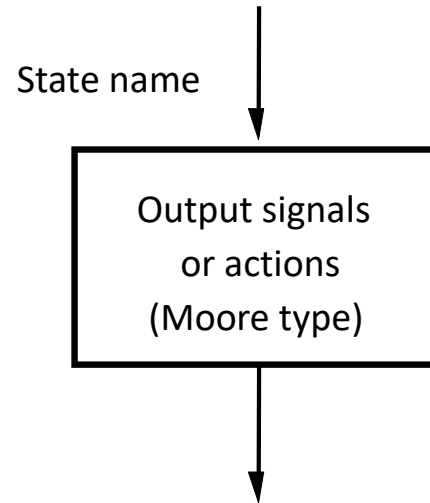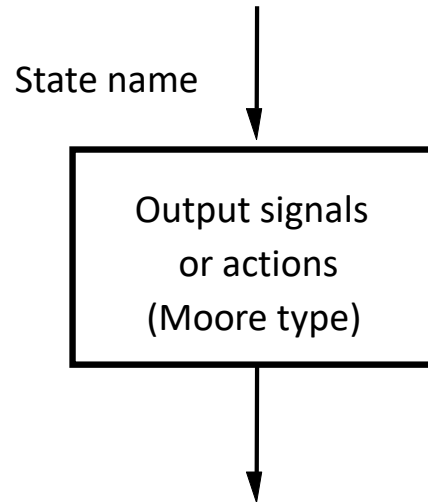
State Box

- **Indicated with a rectangle**
- **Equivalent to a node in the State diagram**
- **The name of the state is written outside the box**
- **Moore-type outputs are written inside the box**
- **Only the output that must be set to 1 is written (by default, if an output is not listed it is set to 0)**

Decision Box

0 (False)

Condition
expression

1 (True)

[Figure 6.81b from the textbook]
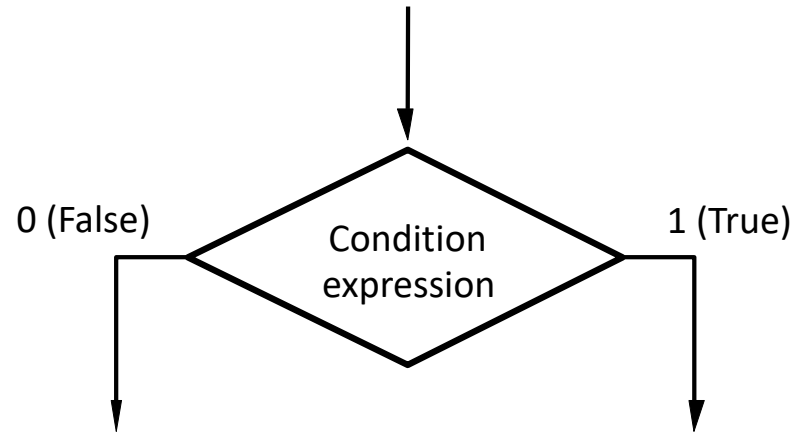
Decision Box
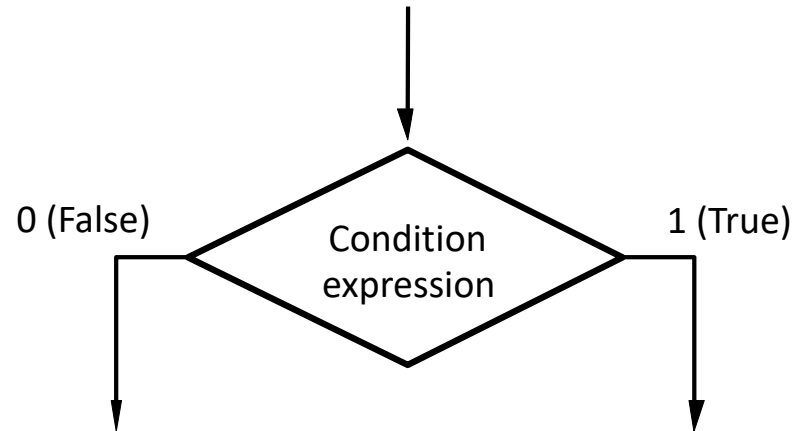
- **Indicated with a diamond shape**
- **Used for a condition expression that must be tested**
- **The exit path is chosen based on the outcome of the test**
- **The condition is on one or more inputs to the FSM**
- **Shortcut notation: w means "is w equal to 1?"**

Conditional Output Box

Conditional outputs
or actions (Mealy type)
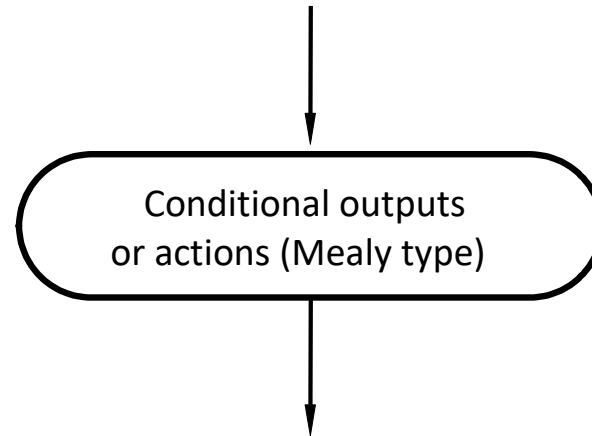
- **Indicated with an oval shape**
- **Used for a Mealy-type output signals**
- **The outputs depend on the state variables and inputs**
- **The condition that determines when such outputs are generated is placed in a separate decision box**

[Figure 6.81c from the textbook]

Some Examples

Moore FSM

Reset

$w = 0$ A / z = 0 $w = 1$ B / z = 0

$w = 0$

$w = 0$ $w = 1$

C / z = 1

$w = 1$

[Figure 6.3 from the textbook]

ASM chart

Reset

A

w 0   1

B

w 0   1

C

z

w 0   1
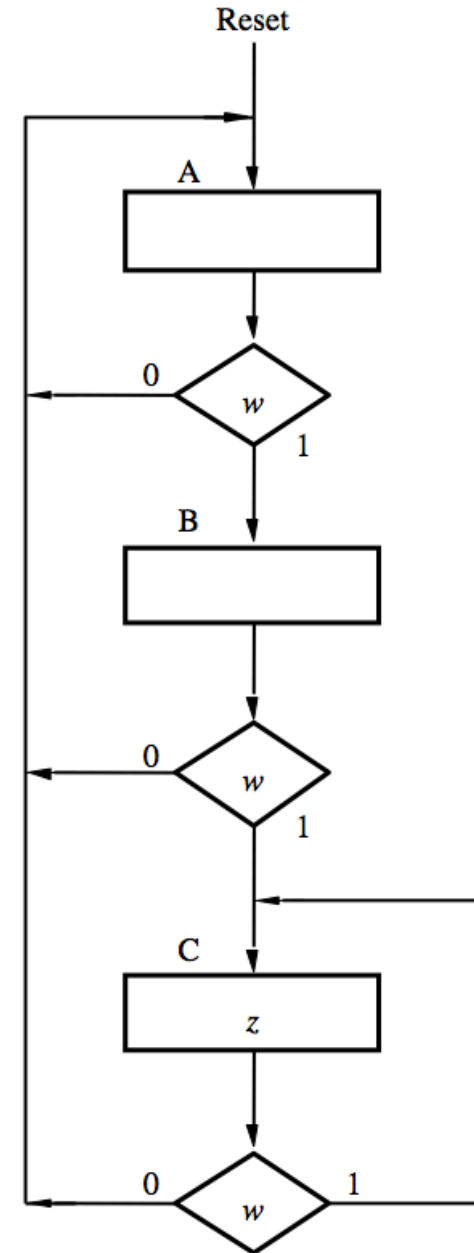
[Figure 6.82 from the textbook]

Mealy FSM

$w = 0/z = 0$ Reset $w = 1/z = 0$

A   B $w = 1/z = 1$

$w = 0/z = 0$
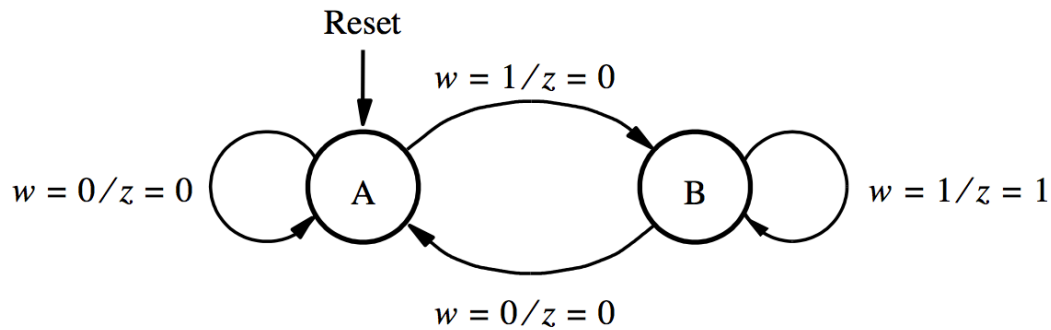
[Figure 6.23 from the textbook]

ASM chart

Reset

A

0   w 1

B

z

0   w 1
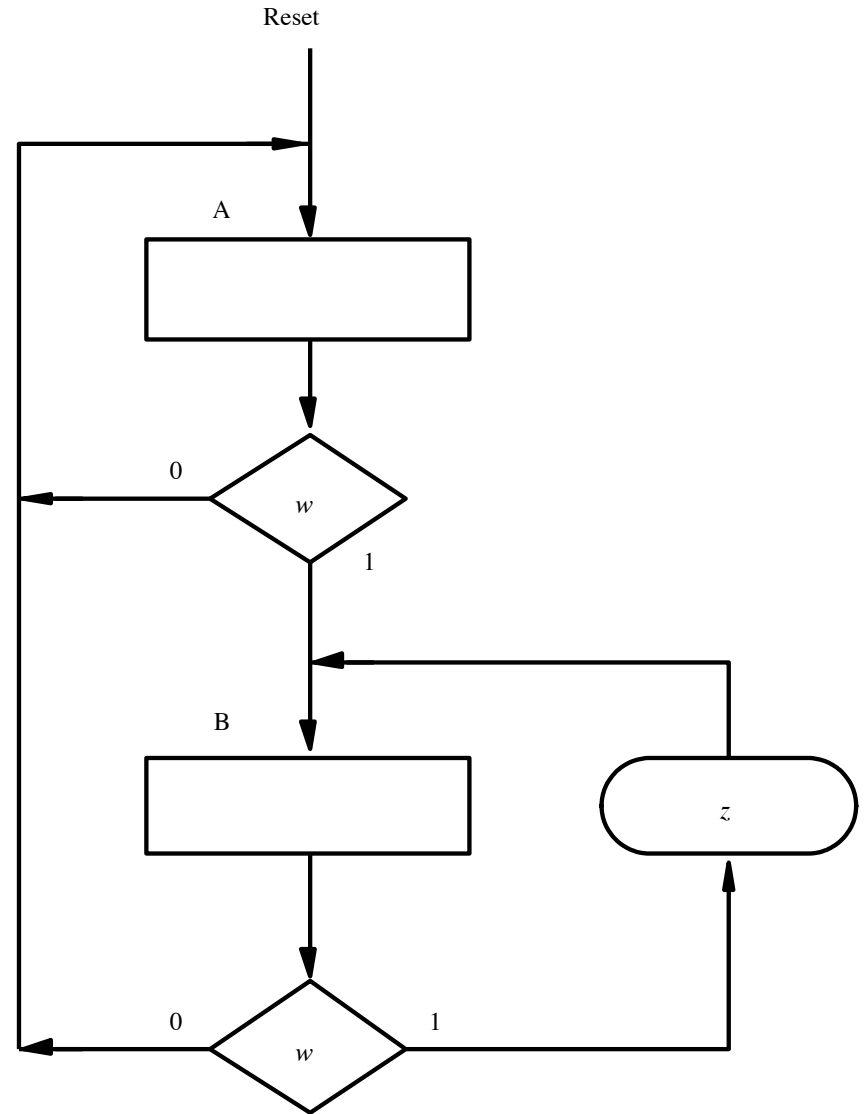
[Figure 6.83 from the textbook]

FSM
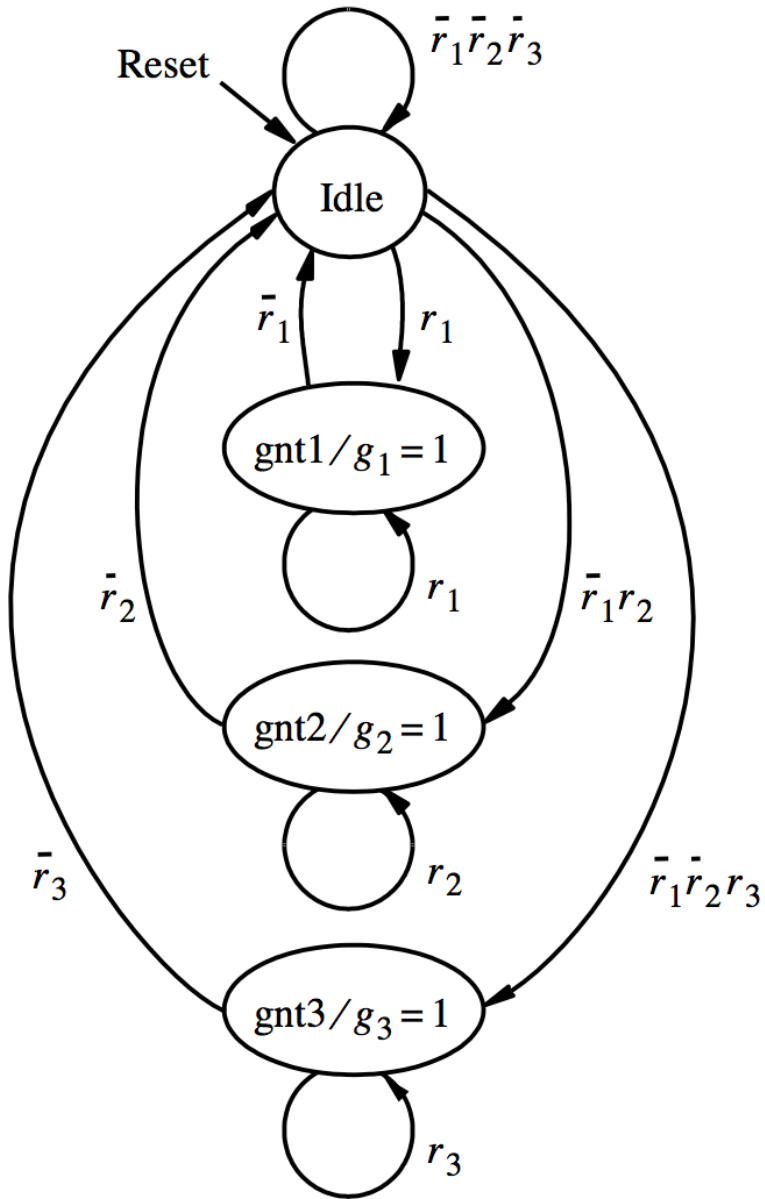
[Figure 6.73 from the textbook]
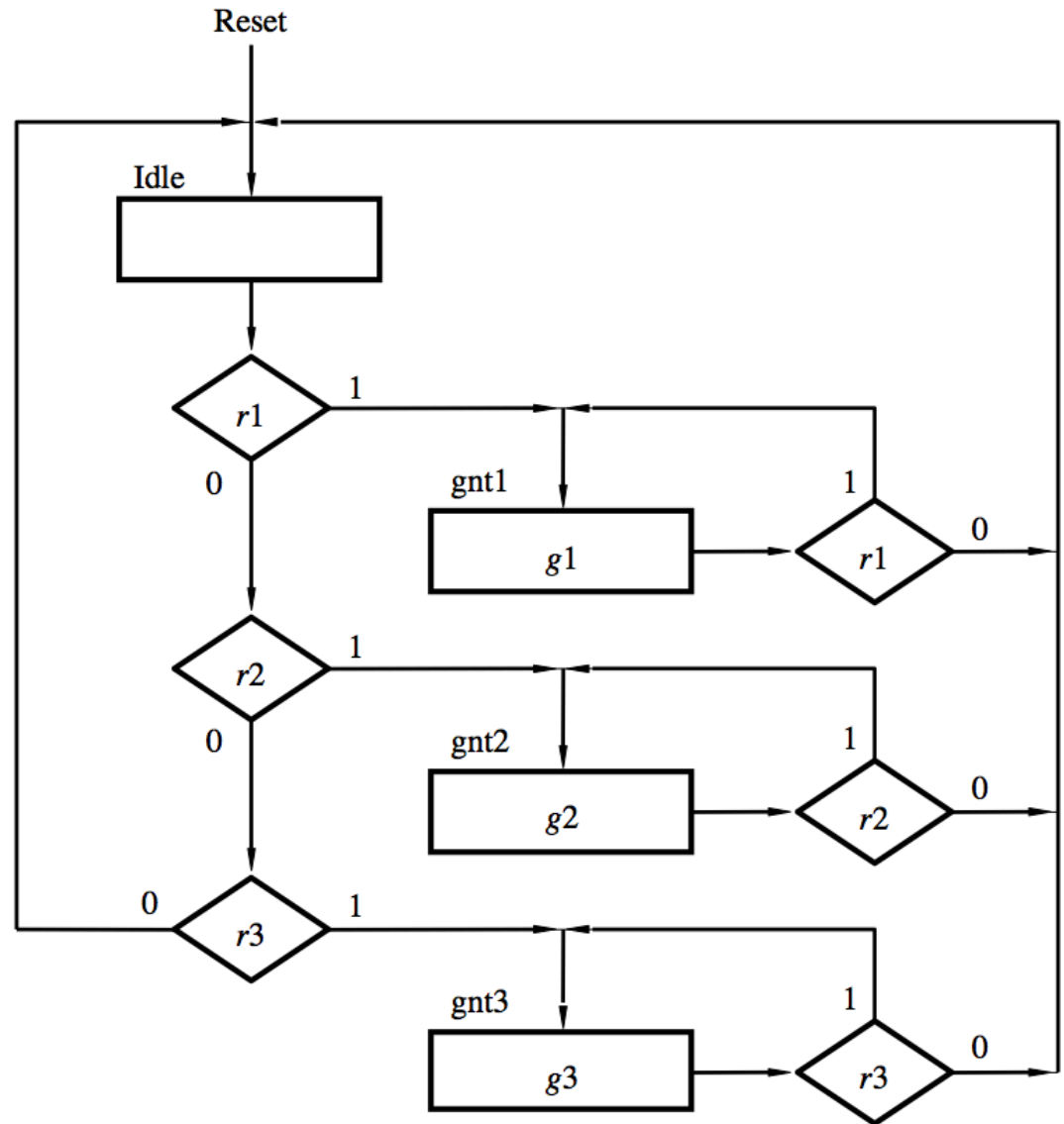
ASM chart

[Figure 6.84 from the textbook]

ASM Chart is different from a Flow Chart

- **The ASM chart implicitly includes timing info**

- **It is assumed that the underlying FSM changes from one state to another on every active clock edge**

- **Flow charts don't make that assumption.**

The general model for a sequential circuit
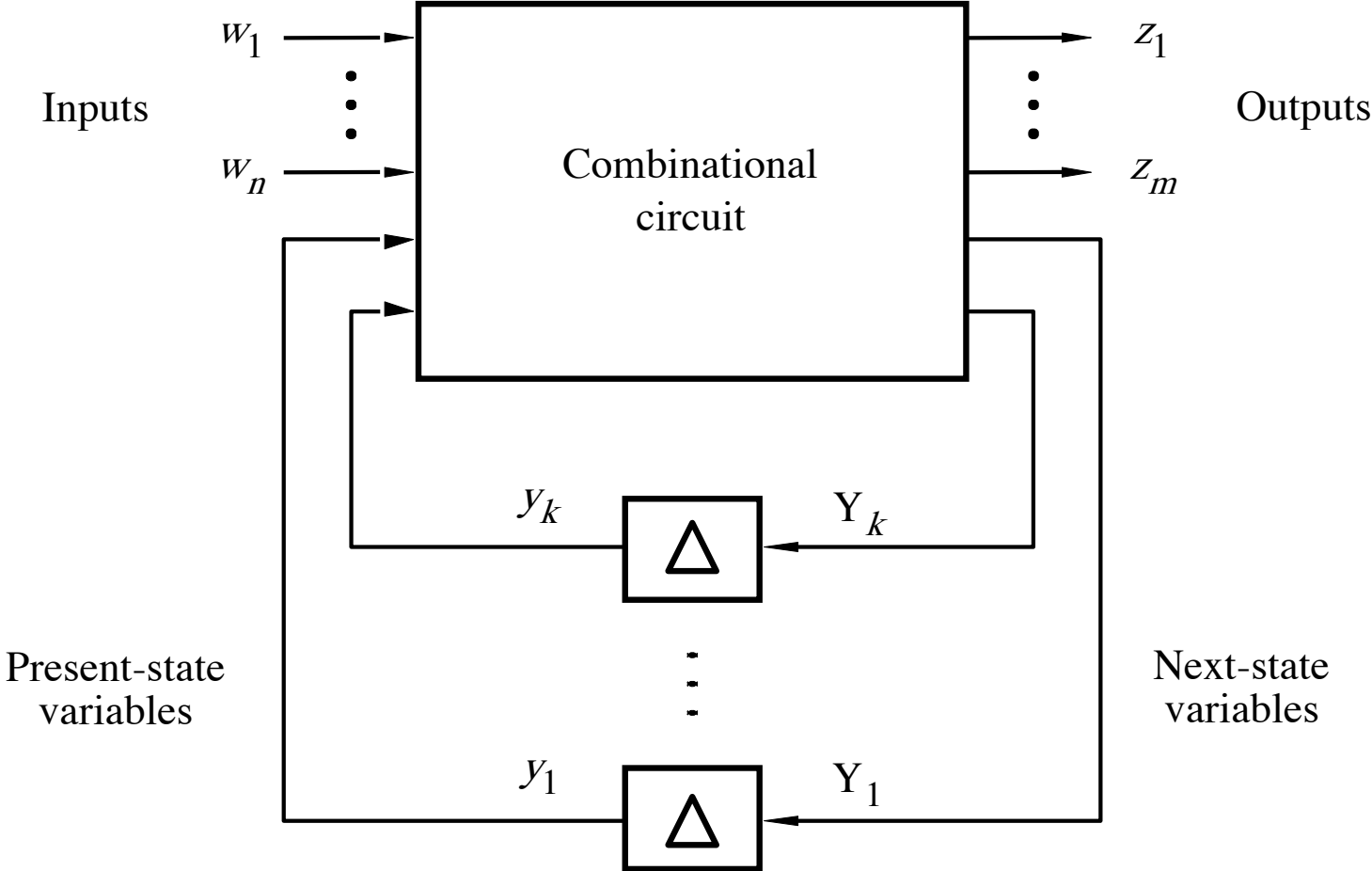
[Figure 6.85 from the textbook]

The general model for a sequential circuit

$$M = (W, Z, S, \varphi, \lambda)$$

- W, Z, and S are finite, nonempty sets of inputs, outputs, and states, respectively.
- φ is the state transition function, such that $S(t+1) = \varphi[W(t), S(t)]$.
- λ is the output function, such that $\lambda(t) = \lambda[S(t)]$ for the Moore model and $\lambda(t) = \lambda[W(t), S(t)]$ for the Mealy model.

Examples of Solved Problems

Example 6.12

Goal

- Design an FSM that detects if the previous two values of the input w were equal to 00 or 11.

- If either condition is true then the output z should be set to 1; otherwise to 0.

State Diagram
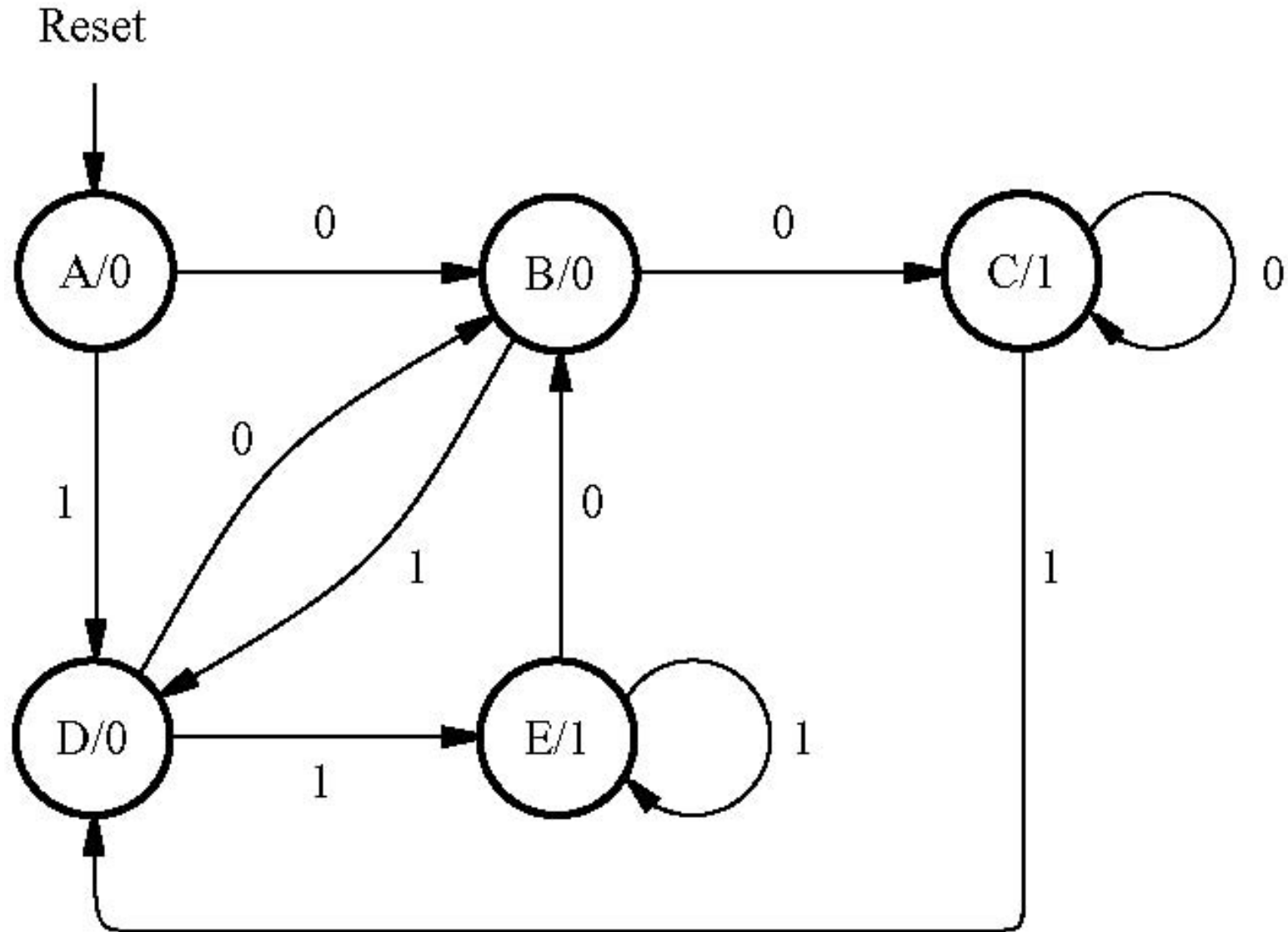
[Figure 6.86 from the textbook]

State Table for the FSM
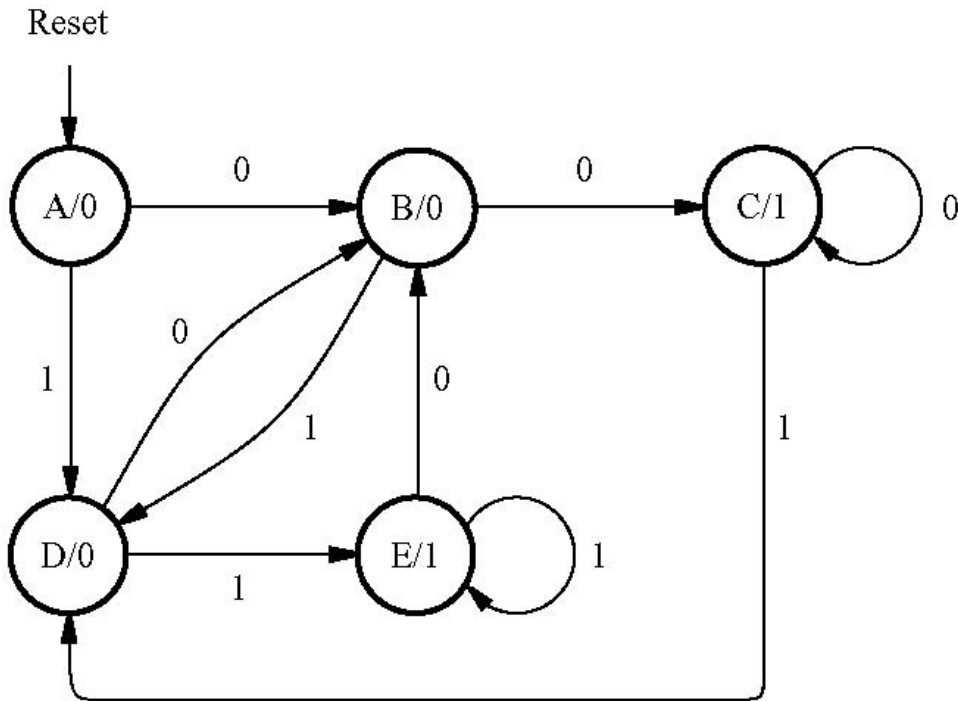
Present state	Next state		Output z
	$w = 0$	$w = 1$	
A	B	D	0
B	C	D	0
C	C	D	1
D	B	E	0
E	B	E	1

[Figure 6.86 from the textbook]   [Figure 6.87 from the textbook]

State Table for the FSM

Present state	Next state		Output z
	$w = 0$	$w = 1$	
A	B	D	0
B	C	D	0
C	C	D	1
D	B	E	0
E	B	E	1

[Figure 6.87 from the textbook]

State-Assigned Table for the FSM

Present state	Next state		Output z
	$w = 0$	$w = 1$	
A	B	D	0
B	C	D	0
C	C	D	1
D	B	E	0
E	B	E	1

Present state $y_3y_2y_1$	Next state		Output z
	$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1

[Figure 6.88 from the textbook]

State-Assigned Table for the FSM

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1

[Figure 6.88 from the textbook]

State-Assigned Table for the FSM

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1

$$z = y_3 + \bar{y}_1 y_2$$

How can we derive this expression?

State-Assigned Table for the FSM

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1
	101	ddd	ddd	d
	110	ddd	ddd	d
	111	ddd	ddd	d

Truth Table for the Output z

	Present state $y_3 y_2 y_1$	Next state		Output z
		$w = 0$ $Y_3 Y_2 Y_1$	$w = 1$ $Y_3 Y_2 Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1
	101	ddd	ddd	d
	110	ddd	ddd	d
	111	ddd	ddd	d

y_3	y_2	y_1	z
0	0	0	
0	0	1	
0	1	0	
0	1	1	
1	0	0	
1	0	1	
1	1	0	
1	1	1	

Truth Table for the Output z

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1
	101	ddd	ddd	d
	110	ddd	ddd	d
	111	ddd	ddd	d

y_3	y_2	y_1	z
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	0
1	0	0	1
1	0	1	d
1	1	0	d
1	1	1	d

Truth Table for the Output z

Present state $y_3y_2y_1$	Next state		Output z
	$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1
	101	ddd	ddd	d
	110	ddd	ddd	d
	111	ddd	ddd	d

y_3	y_2	y_1	z
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	0
1	0	0	1
1	0	1	d
1	1	0	d
1	1	1	d

K-Map for the Output z

$$z$$

$$y_3 y_2$$

y_1	00	01	11	10
0	0	1	d	1
1	0	0	d	d

	Present state $y_3 y_2 y_1$	Next state		Output z
		$w = 0$ $Y_3 Y_2 Y_1$	$w = 1$ $Y_3 Y_2 Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1
	101	ddd	ddd	d
	110	ddd	ddd	d
	111	ddd	ddd	d

y_3	y_2	y_1	z
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	0
1	0	0	1
1	0	1	d
1	1	0	d
1	1	1	d

The Expression for the Output z

Present state $y_3y_2y_1$	Next state		Output z
	$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A 000	001	011	0
B 001	010	011	0
C 010	010	011	1
D 011	001	100	0
E 100	001	100	1
101	ddd	ddd	d
110	ddd	ddd	d
111	ddd	ddd	d

z

y_3y_2 $\overline{y_1}\,y_2$ y_3

y_1

	00	01	11	10
0	0	1	d	1
1	0	0	d	d

y_3	y_2	y_1	z
0	0	0	0
0	0	1	0
0	1	0	1
0	1	1	0
1	0	0	1
1	0	1	d
1	1	0	d
1	1	1	d

State-Assigned Table for the FSM

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1

$$Y_1 = w\bar{y}_1\bar{y}_3 + w\bar{y}_2\bar{y}_3 + \bar{w}y_1y_2 + \bar{w}y_1\bar{y}_2$$

$$Y_2 = y_1\bar{y}_2 + \bar{y}_1y_2 + w\bar{y}_2\bar{y}_3$$

$$Y_3 = wy_3 + wy_1y_2$$

How can we derive these expressions?

Truth Table for Y_3

	Present state $y_3y_2y_1$	Next state		Output z
		$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A	000	001	011	0
B	001	010	011	0
C	010	010	011	1
D	011	001	100	0
E	100	001	100	1
	101	ddd	ddd	d
	110	ddd	ddd	d
	111	ddd	ddd	d

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	0		
0	0	0	1	0		
0	0	1	0	0		
0	0	1	1	0		
0	1	0	0	0		
0	1	0	1	d		
0	1	1	0	d		
0	1	1	1	d		
1	0	0	0	0		
1	0	0	1	0		
1	0	1	0	0		
1	0	1	1	1		
1	1	0	0	1		
1	1	0	1	d		
1	1	1	0	d		
1	1	1	1	d		

Truth Table for Y$_2$

Present state $y_3y_2y_1$	Next state		Output z
	$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A 000	001	011	0
B 001	010	011	0
C 010	010	011	1
D 011	001	100	0
E 100	001	100	1
101	ddd	ddd	d
110	ddd	ddd	d
111	ddd	ddd	d

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	0	0	
0	0	0	1	0	1	
0	0	1	0	0	1	
0	0	1	1	0	0	
0	1	0	0	0	0	
0	1	0	1	d	d	
0	1	1	0	d	d	
0	1	1	1	d	d	
1	0	0	0	0	1	
1	0	0	1	0	1	
1	0	1	0	0	1	
1	0	1	1	1	0	
1	1	0	0	1	0	
1	1	0	1	d	d	
1	1	1	0	d	d	
1	1	1	1	d	d	

Truth Table for Y_1

Present state $y_3y_2y_1$	Next state		Output z
	$w = 0$	$w = 1$	
	$Y_3Y_2Y_1$	$Y_3Y_2Y_1$	
A 000	001	011	0
B 001	010	011	0
C 010	010	011	1
D 011	001	100	0
E 100	001	100	1
101	ddd	ddd	d
110	ddd	ddd	d
111	ddd	ddd	d

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	0	0	1
0	0	0	1	0	1	0
0	0	1	0	0	1	0
0	0	1	1	0	0	1
0	1	0	0	0	0	1
0	1	0	1	d	d	d
0	1	1	0	d	d	d
0	1	1	1	d	d	d
1	0	0	0	0	1	1
1	0	0	1	0	1	1
1	0	1	0	0	1	1
1	0	1	1	1	0	0
1	1	0	0	1	0	0
1	1	0	1	d	d	d
1	1	1	0	d	d	d
1	1	1	1	d	d	d

K-Maps for Y_3, Y_2, Y_1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	0	0	1
0	0	0	1	0	1	0
0	0	1	0	0	1	0
0	0	1	1	0	0	1
0	1	0	0	0	0	1
0	1	0	1	d	d	d
0	1	1	0	d	d	d
0	1	1	1	d	d	d
1	0	0	0	0	1	1
1	0	0	1	0	1	1
1	0	1	0	0	1	1
1	0	1	1	1	0	0
1	1	0	0	1	0	0
1	1	0	1	d	d	d
1	1	1	0	d	d	d
1	1	1	1	d	d	d

Y_3

$w\,y_3$

$y_2\,y_1$

	00	01	11	10
00	0	0	1	0
01	0	d	d	0
11	0	d	d	1
10	0	d	d	0

Y_2

$w\,y_3$

$y_2\,y_1$

	00	01	11	10
00	0	0	0	1
01	1	d	d	1
11	0	d	d	0
10	1	d	d	1

Y_1

$w\,y_3$

$y_2\,y_1$

	00	01	11	10
00	1	1	0	1
01	0	d	d	1
11	1	d	d	0
10	0	d	d	1

K-Maps for Y_3, Y_2, Y_1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	0	0	1
0	0	0	1	0	1	0
0	0	1	0	0	1	0
0	0	1	1	0	0	1
0	1	0	0	0	0	1
0	1	0	1	d	d	d
0	1	1	0	d	d	d
0	1	1	1	d	d	d
1	0	0	0	0	1	1
1	0	0	1	0	1	1
1	0	1	0	0	1	1
1	0	1	1	1	0	0
1	1	0	0	1	0	0
1	1	0	1	d	d	d
1	1	1	0	d	d	d
1	1	1	1	d	d	d

Y_3 — $w\,y_3$ / $y_2\,y_1$

	00	01	11	10
00	0	0	1	0
01	0	d	d	0
11	0	d	d	1
10	0	d	d	0

Y_2 — $w\,y_3$ / $y_2\,y_1$

	00	01	11	10
00	0	0	0	1
01	1	d	d	1
11	0	d	d	0
10	1	d	d	1

Y_1 — $w\,y_3$ / $y_2\,y_1$

	00	01	11	10
00	1	1	0	1
01	0	d	d	1
11	1	d	d	0
10	0	d	d	1

Expressions for Y_3, Y_2, Y_1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	0	0	1
0	0	0	1	0	1	0
0	0	1	0	0	1	0
0	0	1	1	0	0	1
0	1	0	0	0	0	1
0	1	0	1	d	d	d
0	1	1	0	d	d	d
0	1	1	1	d	d	d
1	0	0	0	0	1	1
1	0	0	1	0	1	1
1	0	1	0	0	1	1
1	0	1	1	1	0	0

Y_3 map ($w\,y_3$ across: 00, 01, 11, 10; $y_2\,y_1$ down: 00, 01, 11, 10):

	00	01	11	10
00	0	0	1	0
01	0	d	d	0
11	0	d	d	1
10	0	d	d	0

Y_2 map:

	00	01	11	10
00	0	0	0	1
01	1	d	d	1
11	0	d	d	0
10	1	d	d	1

Y_1 map:

	00	01	11	10
00	1	1	0	1
01	0	d	d	1
11	1	d	d	0
10	0	d	d	1

$$Y_1 = w\bar{y}_1\bar{y}_3 + w\bar{y}_2\bar{y}_3 + \bar{w}y_1y_2 + \bar{w}y_1\bar{y}_2$$

$$Y_2 = y_1\bar{y}_2 + \bar{y}_1y_2 + w\bar{y}_2\bar{y}_3$$

$$Y_3 = wy_3 + wy_1y_2$$

Next State and Output Expressions

$$Y_1 = w\bar{y}_1\bar{y}_3 + w\bar{y}_2\bar{y}_3 + \bar{w}y_1y_2 + \bar{w}y_1\bar{y}_2$$

$$Y_2 = y_1\bar{y}_2 + \bar{y}_1y_2 + w\bar{y}_2\bar{y}_3$$

$$Y_3 = wy_3 + wy_1y_2$$

$$z = y_3 + \bar{y}_1y_2$$

An Improved State-Assigned Table

Present state $y_3y_2y_1$	Next state		Output z
	$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A 000	001	011	0
B 001	010	011	0
C 010	010	011	1
D 011	001	100	0
E 100	001	100	1

[Figure 6.87 from the textbook]

Present state $y_3y_2y_1$	Next state		Output z
	$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A 000	100	110	0
B 100	101	110	0
C 101	101	110	1
D 110	100	111	0
E 111	100	111	1

B,C, D, E − when y_3=1

[Figure 6.89 from the textbook]

An Improved State-Assigned Table

Present state	Next state		Output z
	$w=0$	$w=1$	
A	B	D	0
B	C	D	0
C	C	D	1
D	B	E	0
E	B	E	1

Present state	Next state		Output z
	$w=0$	$w=1$	
A	B	D	0
B	C	D	0
C	C	D	1
D	B	E	0
E	B	E	1

Present state $y_3y_2y_1$	Next state		Output z
	$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A 000	001	011	0
B 001	010	011	0
C 010	010	011	1
D 011	001	100	0
E 100	001	100	1

Present state $y_3y_2y_1$	Next state		Output z
	$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A 000	100	110	0
B 100	101	110	0
C 101	101	110	1
D 110	100	111	0
E 111	100	111	1

B,C, D, E – when y_3=1

[Figure 6.87 from the textbook]

[Figure 6.89 from the textbook]

An Improved State-Assigned Table

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	100	110	0
B	100	101	110	0
C	101	101	110	1
D	110	100	111	0
E	111	100	111	1

An Improved State-Assigned Table

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	100	110	0
B	100	101	110	0
C	101	101	110	1
D	110	100	111	0
E	111	100	111	1

cut here

An Improved State-Assigned Table

Present state $y_3y_2y_1$	Next state		Output z
	$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A 000	100	110	0
001	ddd	ddd	d
010	ddd	ddd	d
011	ddd	ddd	d
B 100	101	110	0
C 101	101	110	1
D 110	100	111	0
E 111	100	111	1

Truth Table for the Output z

	Present state $y_3y_2y_1$	Next state		Output z
		$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A	000	100	110	0
	001	ddd	ddd	d
	010	ddd	ddd	d
	011	ddd	ddd	d
B	100	101	110	0
C	101	101	110	1
D	110	100	111	0
E	111	100	111	1

y_3	y_2	y_1	z
0	0	0	0
0	0	1	d
0	1	0	d
0	1	1	d
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

Expression for the Output z

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	100	110	0
	001	ddd	ddd	d
	010	ddd	ddd	d
	011	ddd	ddd	d
B	100	101	110	0
C	101	101	110	1
D	110	100	111	0
E	111	100	111	1

z

y_3y_2

y_1

	00	01	11	10
0	0	d	0	0
1	d	d	1	1

y_1

y_3	y_2	y_1	z
0	0	0	0
0	0	1	d
0	1	0	d
0	1	1	d
1	0	0	0
1	0	1	1
1	1	0	0
1	1	1	1

Truth Table for Y$_3$

Present state $y_3y_2y_1$	Next state		Output z
	$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A 000	100	110	0
001	ddd	ddd	d
010	ddd	ddd	d
011	ddd	ddd	d
B 100	101	110	0
C 101	101	110	1
D 110	100	111	0
E 111	100	111	1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	1		
0	0	0	1	d		
0	0	1	0	d		
0	0	1	1	d		
0	1	0	0	1		
0	1	0	1	1		
0	1	1	0	1		
0	1	1	1	1		
1	0	0	0	1		
1	0	0	1	d		
1	0	1	0	d		
1	0	1	1	d		
1	1	0	0	1		
1	1	0	1	1		
1	1	1	0	1		
1	1	1	1	1		

Truth Table for Y$_2$

Present state $y_3y_2y_1$	Next state $w=0$ $Y_3Y_2Y_1$	Next state $w=1$ $Y_3Y_2Y_1$	Output z
A 000	100	110	0
001	ddd	ddd	d
010	ddd	ddd	d
011	ddd	ddd	d
B 100	101	110	0
C 101	101	110	1
D 110	100	111	0
E 111	100	111	1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	1	0	
0	0	0	1	d	d	
0	0	1	0	d	d	
0	0	1	1	d	d	
0	1	0	0	1	0	
0	1	0	1	1	0	
0	1	1	0	1	0	
0	1	1	1	1	0	
1	0	0	0	1	1	
1	0	0	1	d	d	
1	0	1	0	d	d	
1	0	1	1	d	d	
1	1	0	0	1	1	
1	1	0	1	1	1	
1	1	1	0	1	1	
1	1	1	1	1	1	

Truth Table for Y_1

Present state $y_3y_2y_1$	Next state		Output z
	$w=0$ $Y_3Y_2Y_1$	$w=1$ $Y_3Y_2Y_1$	
A 000	100	110	0
001	**ddd**	**ddd**	**d**
010	**ddd**	**ddd**	**d**
011	**ddd**	**ddd**	**d**
B 100	101	110	0
C 101	101	110	1
D 110	100	111	0
E 111	100	111	1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	1	0	0
0	0	0	1	d	d	d
0	0	1	0	d	d	d
0	0	1	1	d	d	d
0	1	0	0	1	0	1
0	1	0	1	1	0	1
0	1	1	0	1	0	0
0	1	1	1	1	0	0
1	0	0	0	1	1	0
1	0	0	1	d	d	d
1	0	1	0	d	d	d
1	0	1	1	d	d	d
1	1	0	0	1	1	0
1	1	0	1	1	1	0
1	1	1	0	1	1	1
1	1	1	1	1	1	1

K-Maps for Y_3, Y_2, Y_1

Y_3

$y_2 y_1$ \ $w y_3$	00	01	11	10
00	1	1	1	1
01	d	1	1	d
11	d	1	1	d
10	d	1	1	d

Y_2

$y_2 y_1$ \ $w y_3$	00	01	11	10
00	0	0	1	1
01	d	0	1	d
11	d	0	1	d
10	d	0	1	d

Y_1

$y_2 y_1$ \ $w y_3$	00	01	11	10
00	0	1	0	0
01	d	1	0	d
11	d	0	1	d
10	d	0	1	d

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	1	0	0
0	0	0	1	d	d	d
0	0	1	0	d	d	d
0	0	1	1	d	d	d
0	1	0	0	1	0	1
0	1	0	1	1	0	1
0	1	1	0	1	0	0
0	1	1	1	1	0	0
1	0	0	0	1	1	0
1	0	0	1	d	d	d
1	0	1	0	d	d	d
1	0	1	1	d	d	d
1	1	0	0	1	1	0
1	1	0	1	1	1	0
1	1	1	0	1	1	1
1	1	1	1	1	1	1

K-Maps for Y_3, Y_2, Y_1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	1	0	0
0	0	0	1	d	d	d
0	0	1	0	d	d	d
0	0	1	1	d	d	d
0	1	0	0	1	0	1
0	1	0	1	1	0	1
0	1	1	0	1	0	0
0	1	1	1	1	0	0
1	0	0	0	1	1	0
1	0	0	1	d	d	d
1	0	1	0	d	d	d
1	0	1	1	d	d	d
1	1	0	0	1	1	0
1	1	0	1	1	1	0
1	1	1	0	1	1	1
1	1	1	1	1	1	1

Y_3 — $w\,y_3$ / $y_2\,y_1$

	00	01	11	10
00	1	1	1	1
01	d	1	1	d
11	d	1	1	d
10	d	1	1	d

Y_2 — $w\,y_3$ / $y_2\,y_1$

	00	01	11	10
00	0	0	1	1
01	d	0	1	d
11	d	0	1	d
10	d	0	1	d

Y_1 — $w\,y_3$ / $y_2\,y_1$

	00	01	11	10
00	0	1	0	0
01	d	1	0	d
11	d	0	1	d
10	d	0	1	d

K-Maps for Y_3, Y_2, Y_1

w	y_3	y_2	y_1	Y_3	Y_2	Y_1
0	0	0	0	1	0	0
0	0	0	1	d	d	d
0	0	1	0	d	d	d
0	0	1	1	d	d	d
0	1	0	0	1	0	1
0	1	0	1	1	0	1
0	1	1	0	1	0	0
0	1	1	1	1	0	0
1	0	0	0	1	1	0
1	0	0	1	d	d	d
1	0	1	0	d	d	d
1	0	1	1	d	d	d
1	1	0	0	1	1	0
1	1	0	1	1	1	0
1	1	1	0	1	1	1
1	1	1	1	1	1	1

Y_3

$Y_2 Y_1$ \ $w\,y_3$	00	01	11	10
00	1	1	1	1
01	d	1	1	d
11	d	1	1	d
10	d	1	1	d

Y_2

$Y_2 Y_1$ \ $w\,y_3$	00	01	11	10
00	0	0	1	1
01	d	0	1	d
11	d	0	1	d
10	d	0	1	d

Y_1

$Y_2 Y_1$ \ $w\,y_3$	00	01	11	10
00	0	1	0	0
01	d	1	0	d
11	d	0	1	d
10	d	0	1	d

$$Y_1 = wy_2 + \overline{w}y_3\overline{y}_2$$

$$Y_2 = w$$

$$Y_3 = 1$$

An Improved State-Assigned Table

	Present state $y_3y_2y_1$	Next state		Output z
		$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A	000	100	110	0
B	100	101	110	0
C	101	101	110	1
D	110	100	111	0
E	111	100	111	1

$$Y_1 = wy_2 + \overline{w}y_3\overline{y}_2$$

$$Y_2 = w$$

$$Y_3 = 1$$

$$z = y_1$$

An Improved State-Assigned Table

Present state $y_3y_2y_1$	Next state		Output z
	$w = 0$ $Y_3Y_2Y_1$	$w = 1$ $Y_3Y_2Y_1$	
A 000	100	110	0
B 100	101	110	0
C 101	101	110	1
D 110	100	111	0
E 111	100	111	1

$$Y_1 = wy_2 + \overline{w}\,\overline{y_3}\,\overline{y_2}$$

$$Y_2 = w$$

$$Y_3 = 1$$

$$z = y_1$$

The Circuit Diagram

$$Y_1 = w\, y_2 + \overline{w}\, y_3\, \overline{y_2}$$
$$Y_2 = w$$
$$Y_3 = 1$$
$$z = y_1$$

The Circuit Diagram

this is always 1,
except when reset_n=0

$$Y_1 = w\, y_2 + \overline{w}\, y_3\, \overline{y_2}$$
$$Y_2 = w$$
$$Y_3 = 1$$
$$z = y_1$$
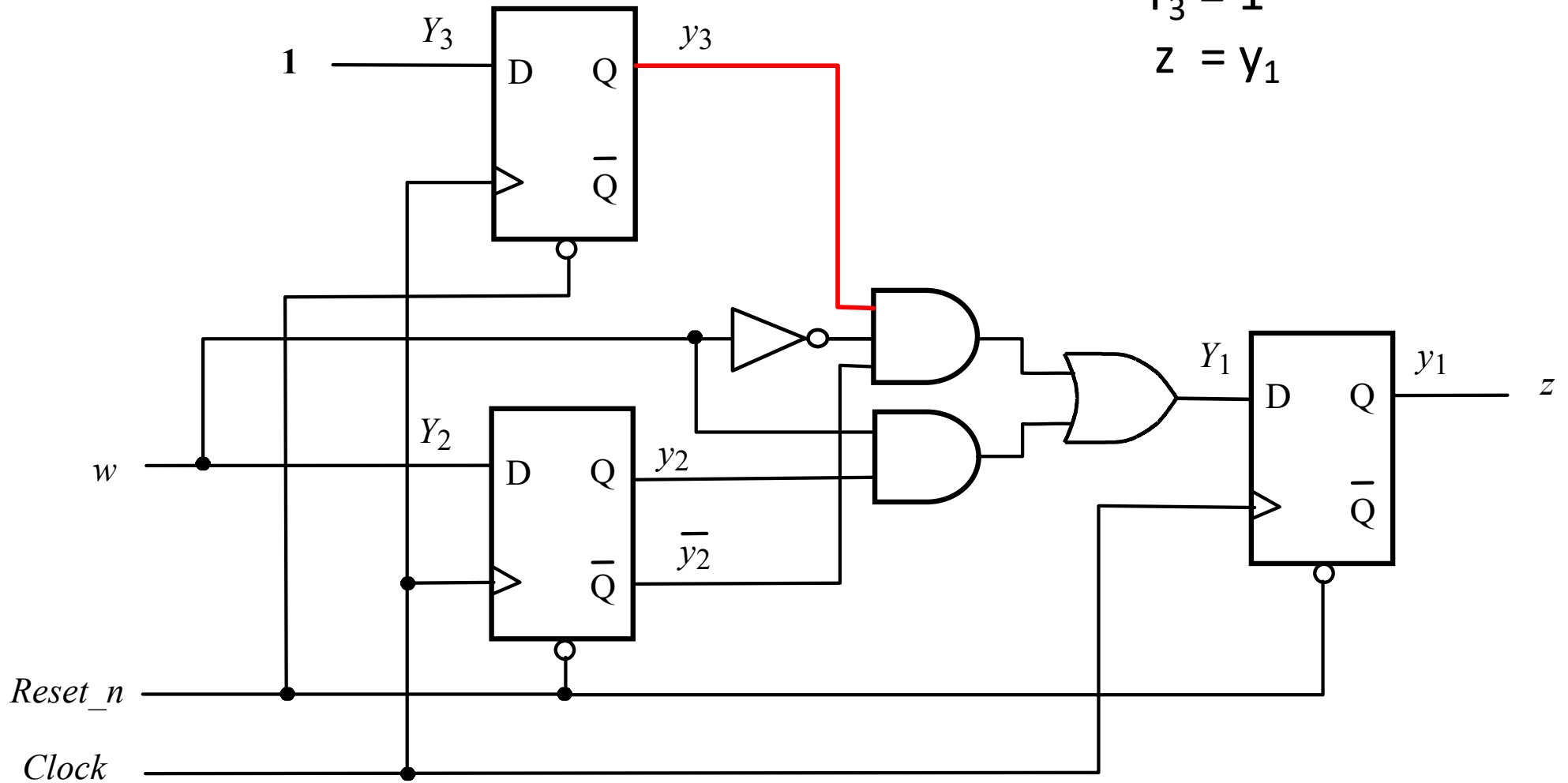
The Circuit Diagram

$$Y_1 = w\ y_2 + \overline{w}\ \cancel{y_3}\ \overline{y_2}$$
$$Y_2 = w$$
$$\cancel{Y_3 = 1}$$
$$z = y_1$$
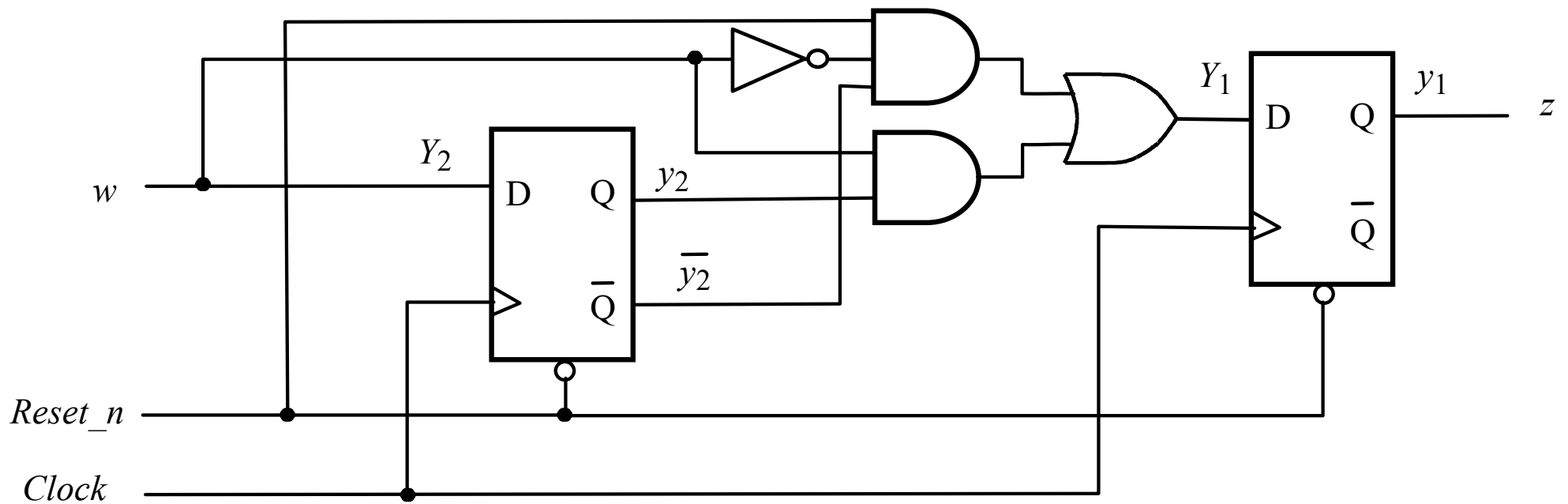
State Diagram
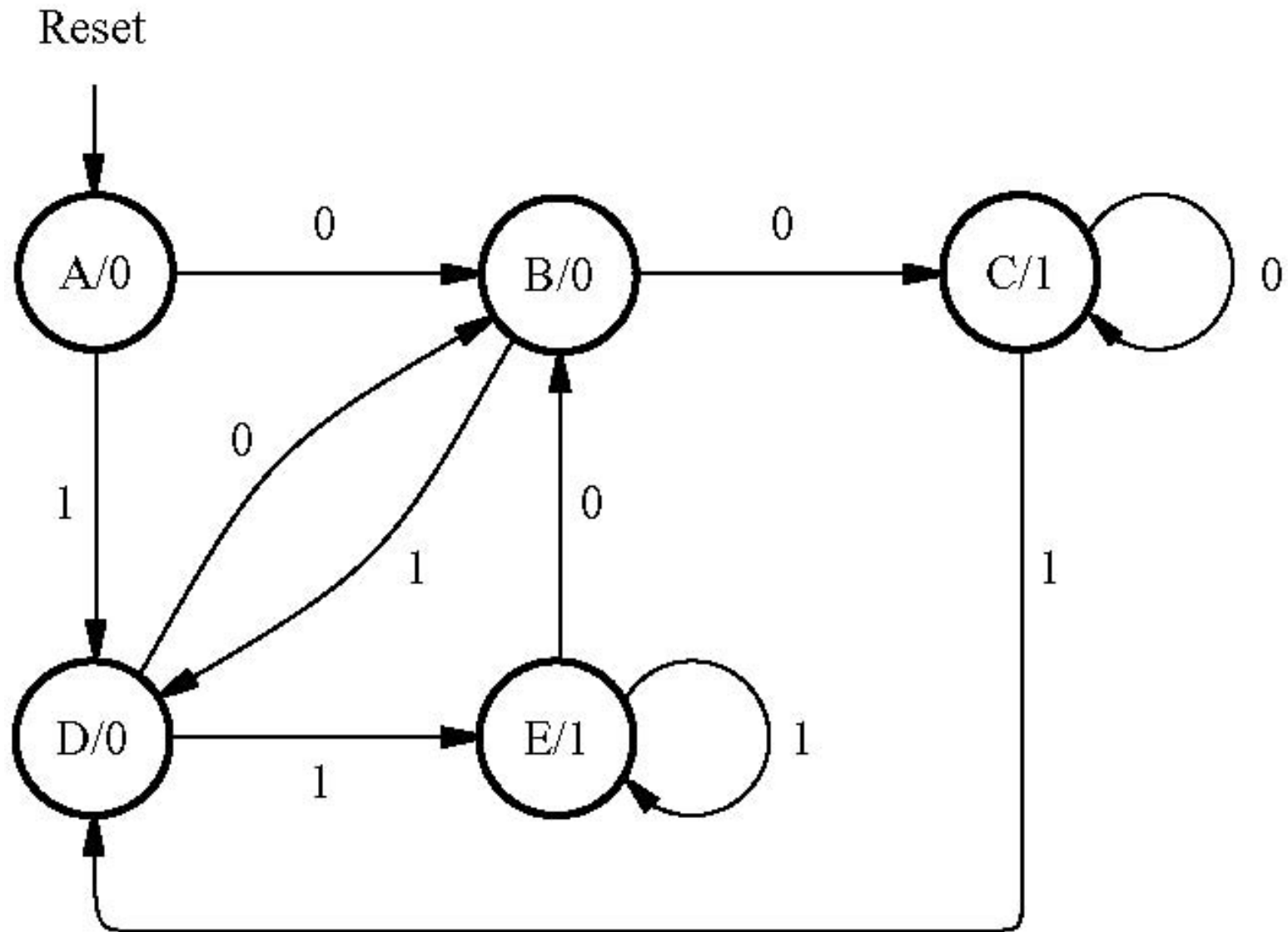
[Figure 6.86 from the textbook]

Example 6.13

Goal

- **Design an FSM that detects if the previous two values of the input w were equal to 00 or 11.**

- **But do this with two different FSMs. The first one detects two consecutive 1's. The second one detects two consecutive 0's.**

- **If either condition (i.e., output of FSM) is true then the output z should be set to 1; otherwise to 0.**

Example 6.13

(Construct the first FSM)

FSM to detect two consecutive 1's
(this was the first example in Chapter 6)
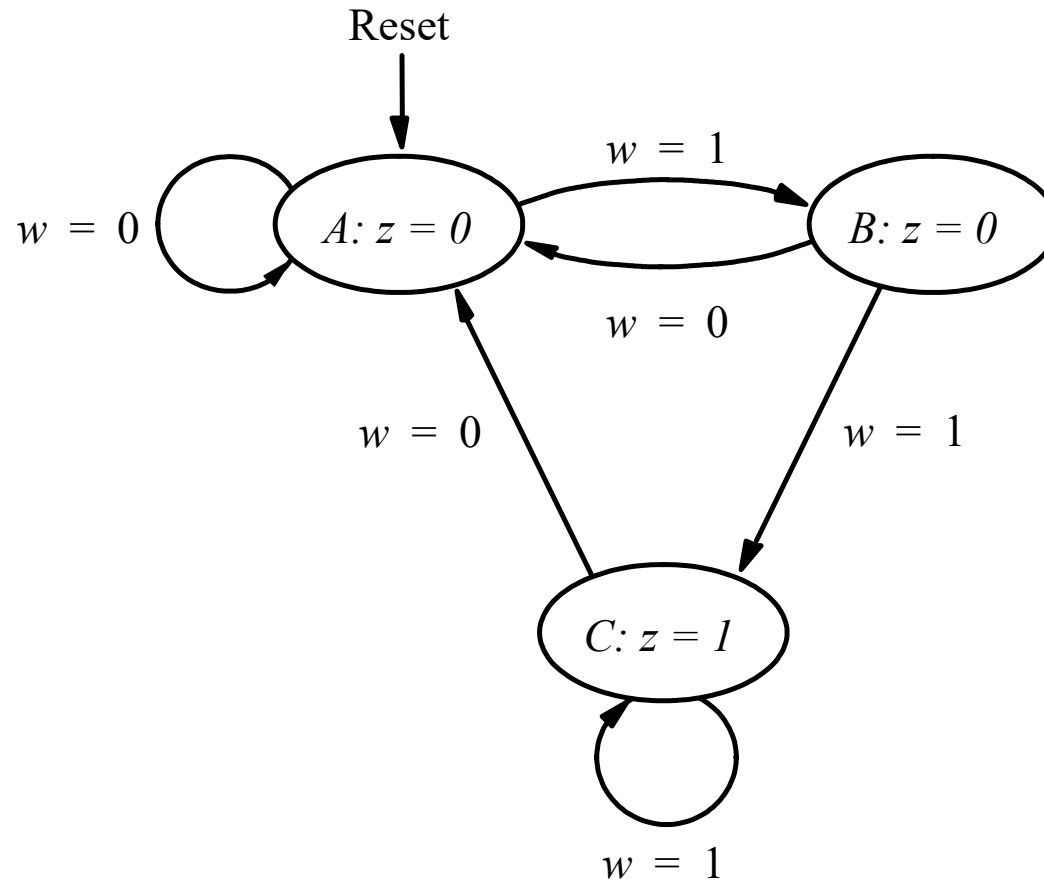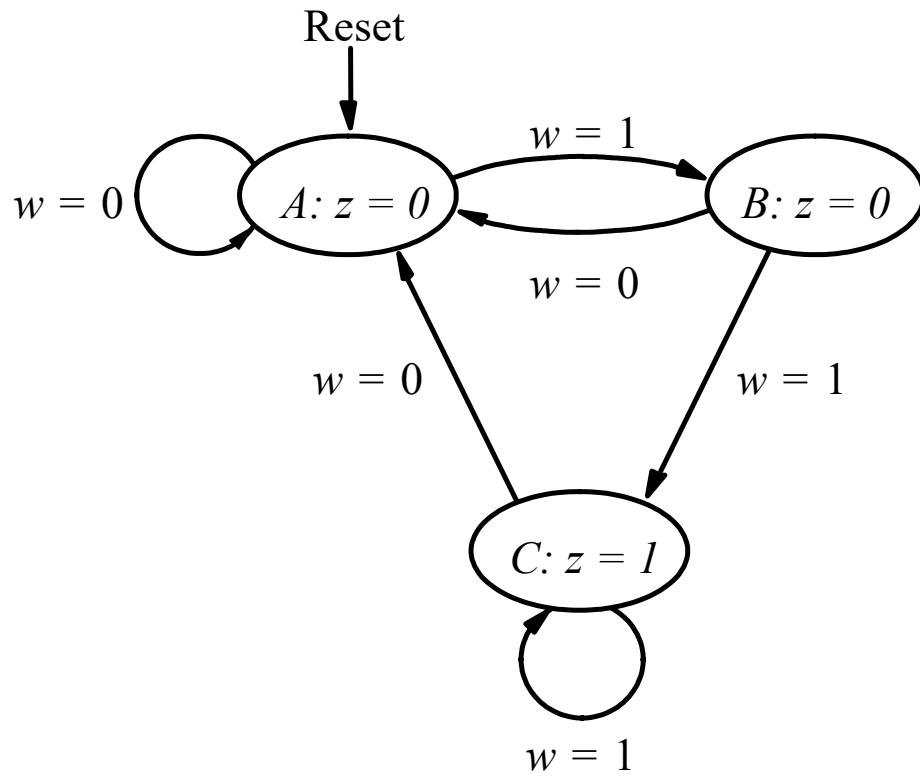
Reset

$w = 1$

$w = 0$ *A: z = 0*   *B: z = 0*

$w = 0$

$w = 0$ $w = 1$

C: z = 1

$w = 1$

[Figure 6.3 from the textbook]

Present state	Next state		Output z
	$w = 0$	$w = 1$	
A B C			

Reset

$w = 0$

$A: z = 0$

$w = 1$

$B: z = 0$

$w = 0$

$w = 0$

$w = 1$

$C: z = 1$

$w = 1$
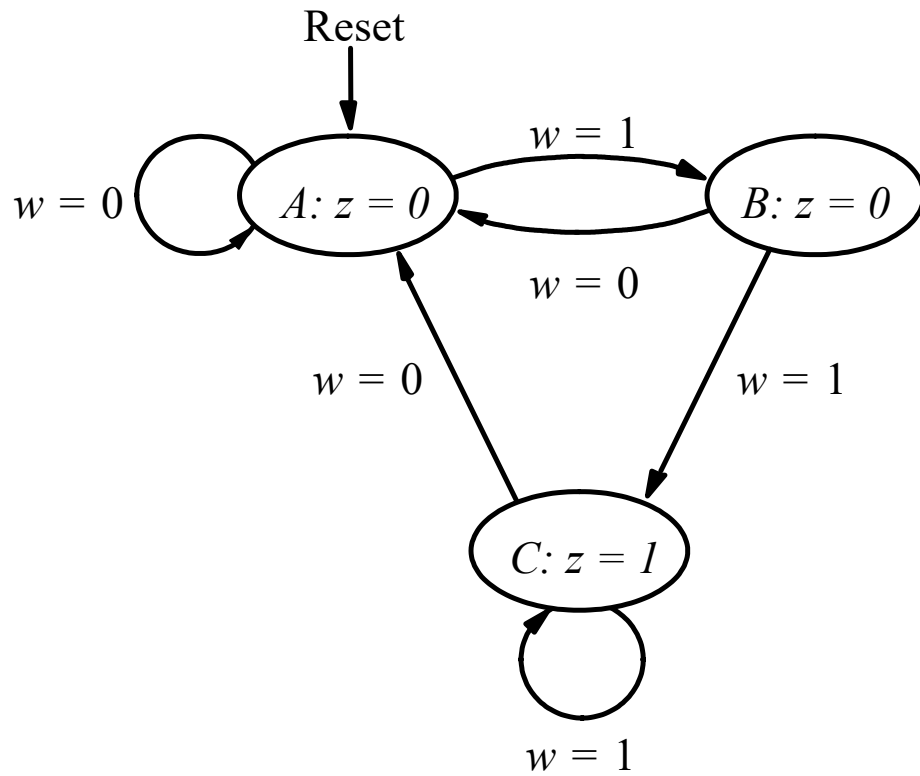
Present state	Next state		Output z
	$w = 0$	$w = 1$	
A	A	B	0
B	A	C	0
C	A	C	1

[Figure 6.4 from the textbook]

A Better State Encoding

Present state	Next state		Output z
	$w = 0$	$w = 1$	
A	A	B	0
B	A	C	0
C	A	C	1

Suppose we encoded our states another way:

A ~ 00

B ~ 01

C ~ 11

A Better State Encoding

Present state	Next state		Output z
	w = 0	w = 1	
A	A	B	0
B	A	C	0
C	A	C	1

Present state	Next state		Output z
	w = 0	w = 1	

A ~ 00

B ~ 01

C ~ 11

A Better State Encoding

Present state	Next state		Output z
	$w = 0$	$w = 1$	
A	A	B	0
B	A	C	0
C	A	C	1

	Present state $y_2 y_1$	Next state		Output z
		$w = 0$ $Y_2 Y_1$	$w = 1$ $Y_2 Y_1$	
A	00	00	01	0
B	01	00	11	0
C	11	00	11	1
	10	dd	dd	d

Let's Derive the Logic Expressions

Present state	Next state		Output
	$w = 0$	$w = 1$	z
$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	
A 00	00	01	0
B 01	00	11	0
C 11	00	11	1
10	dd	dd	d

[Figure 6.16 from the textbook]

Let's Derive the Logic Expressions

	Present state	Next state		Output
		$w = 0$	$w = 1$	z
	$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	
A	00	00	01	0
B	01	00	11	0
C	11	00	11	1
	10	dd	dd	d

Warning:
This table does not enumerate $y_2 y_1$, in the standard way, so be careful when filling out the K-Map.

Y_2

$y_2 y_1$

w

	00	01	11	10
0				
1				

Y_1

$y_2 y_1$

w

	00	01	11	10
0				
1				

z

y_1

y_2

	0	1
0		
1		

Let's Derive the Logic Expressions

Present state	Next state		Output
	$w = 0$	$w = 1$	z
y_2y_1	Y_2Y_1	Y_2Y_1	
A	00	00	01	0
B	01	00	11	0
C	11	00	11	1
	10	dd	dd	d

Y_2

w \ y_2y_1	00	01	11	10
0	0	0	0	d
1	0	1	1	d

$$Y_2(w, y_2, y_1) = wy_1$$

Y_1

w \ y_2y_1	00	01	11	10
0	0	0	0	d
1	1	1	1	d

$$Y_1(w, y_2, y_1) = w$$

z

y_2 \ y_1	0	1
0	0	0
1	d	1

$$z(y_2, y_1) = y_2$$

Original State Encodings

Y_1

w \ $y_2 y_1$	00	01	11	10
0	0	0	d	0
1	1	0	d	0

Y_2

w \ $y_2 y_1$	00	01	11	10
0	0	0	d	0
1	0	1	d	1

y_2 \ z y_1	0	1
0	0	0
1	1	d

New State Encodings

Y_1

w \ $y_2 y_1$	00	01	11	10
0	0	0	0	d
1	1	1	1	d

Y_2

w \ $y_2 y_1$	00	01	11	10
0	0	0	0	d
1	0	1	1	d

y_2 \ z y_1	0	1
0	0	0
1	d	1
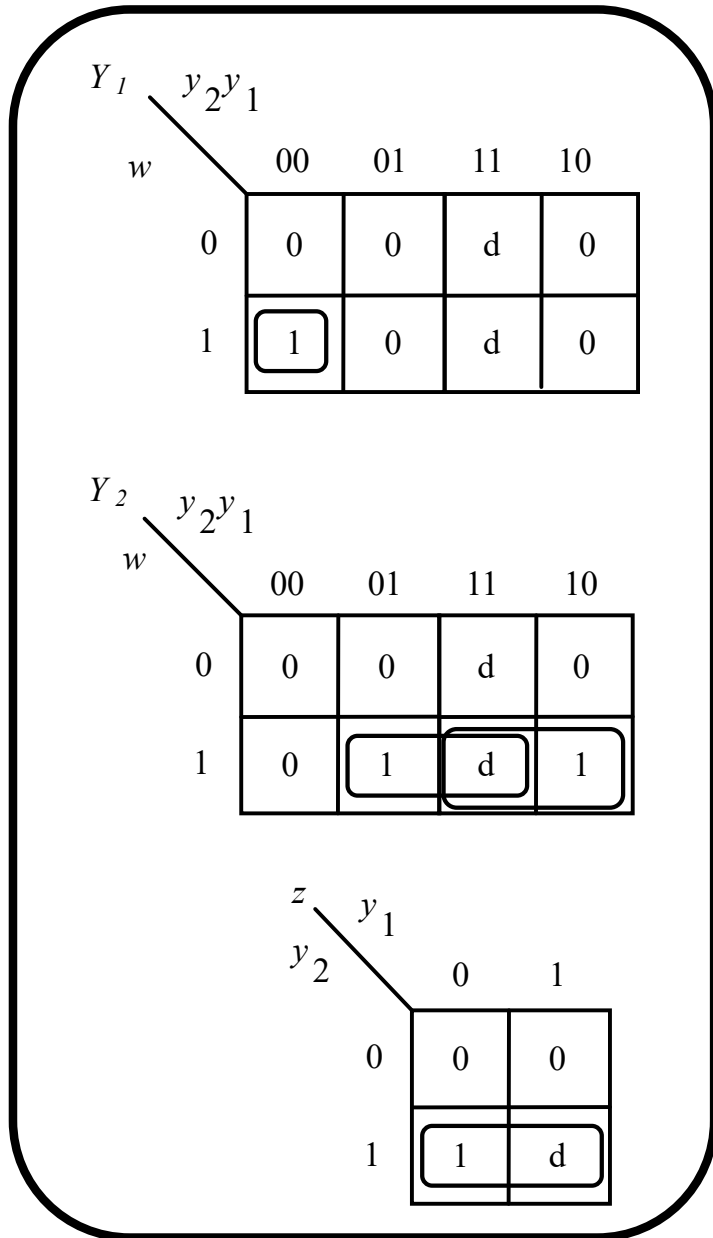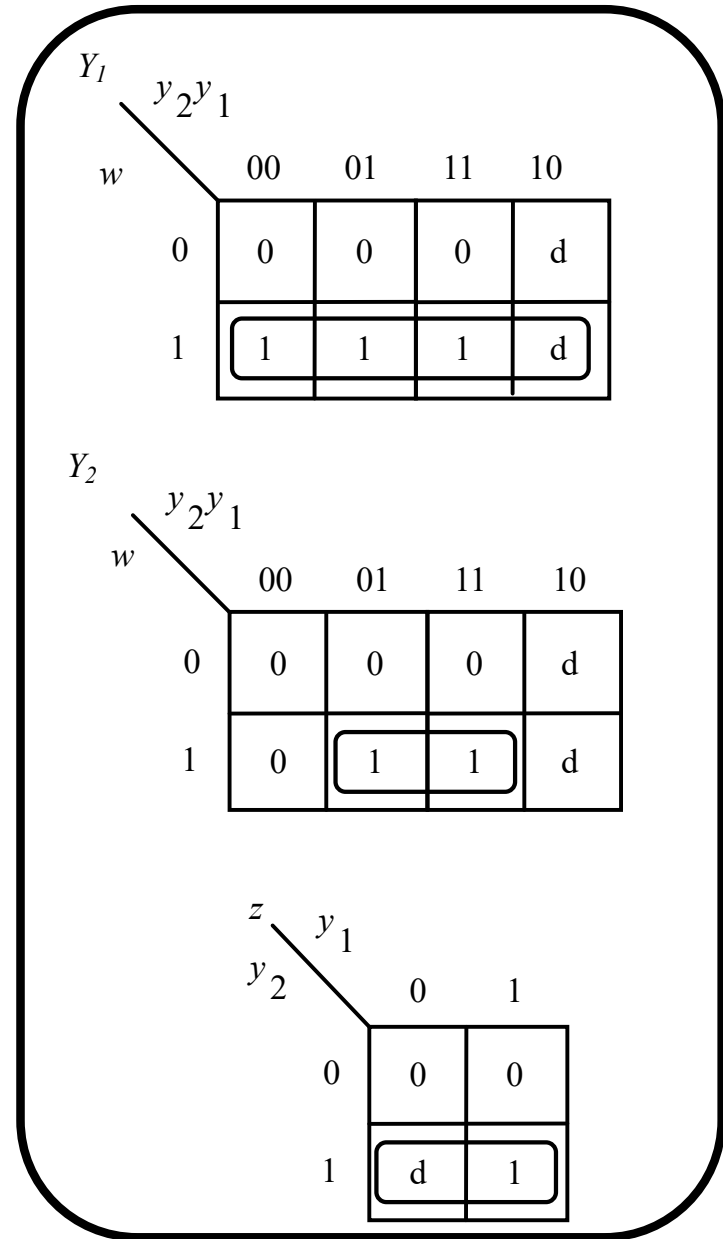
The Circuit Diagram

$$Y_1(w, y_2, y_1) = w$$

$$Y_2(w, y_2, y_1) = wy_1$$

$$z(y_2, y_1) = y_2$$
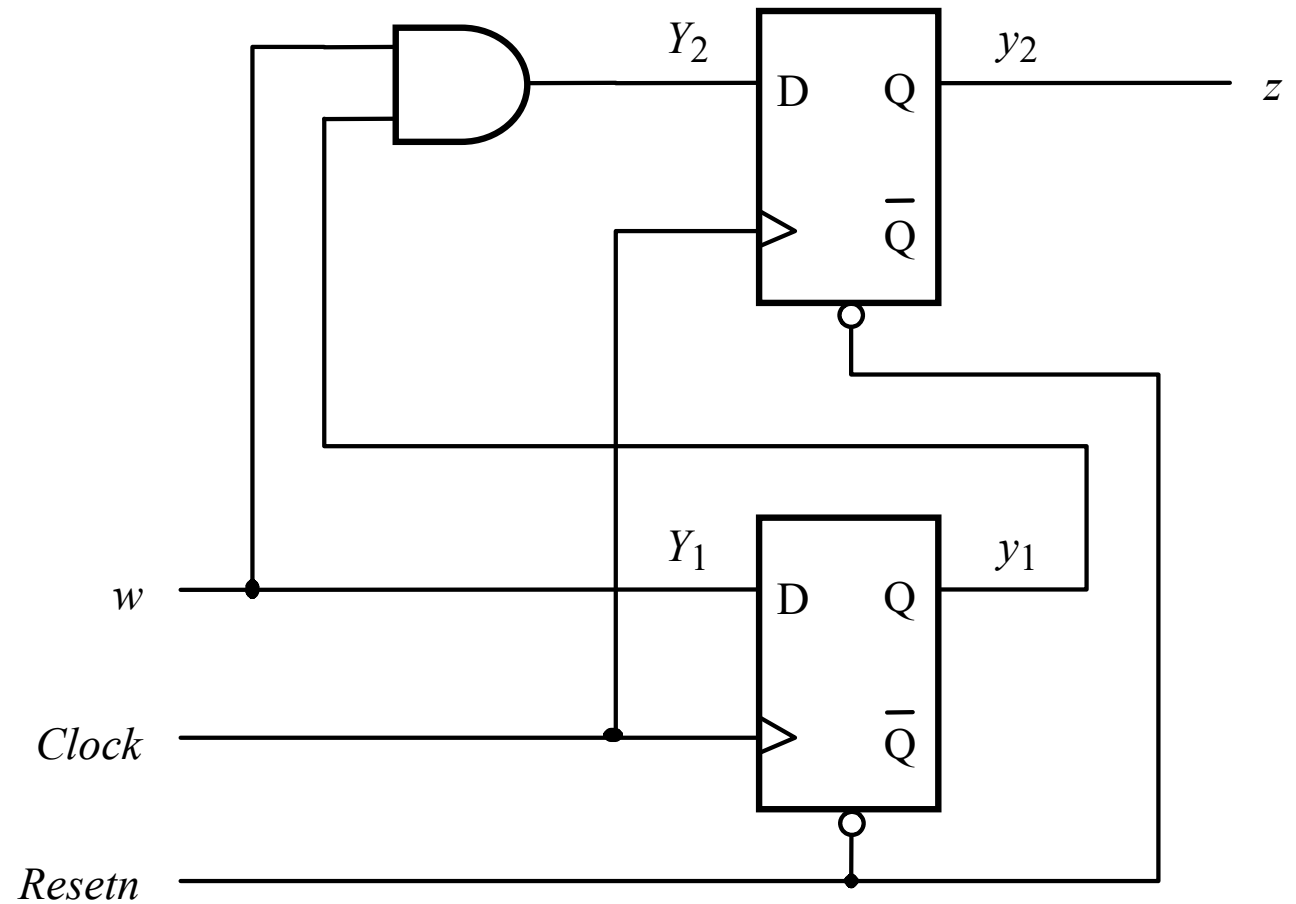
Example 6.13

(Construct the second FSM)

FSM to detect two consecutive 0's

Reset

$w = 1$

$D: z = 0$
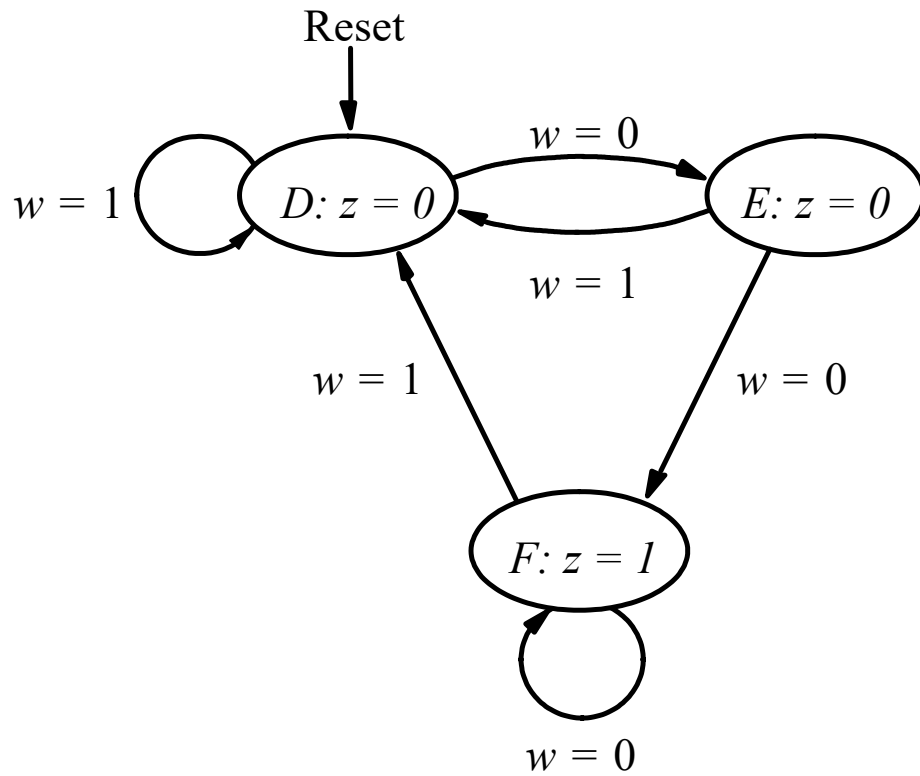
$w = 0$

$E: z = 0$

$w = 1$

$w = 1$

$w = 0$

$F: z = 1$

$w = 0$
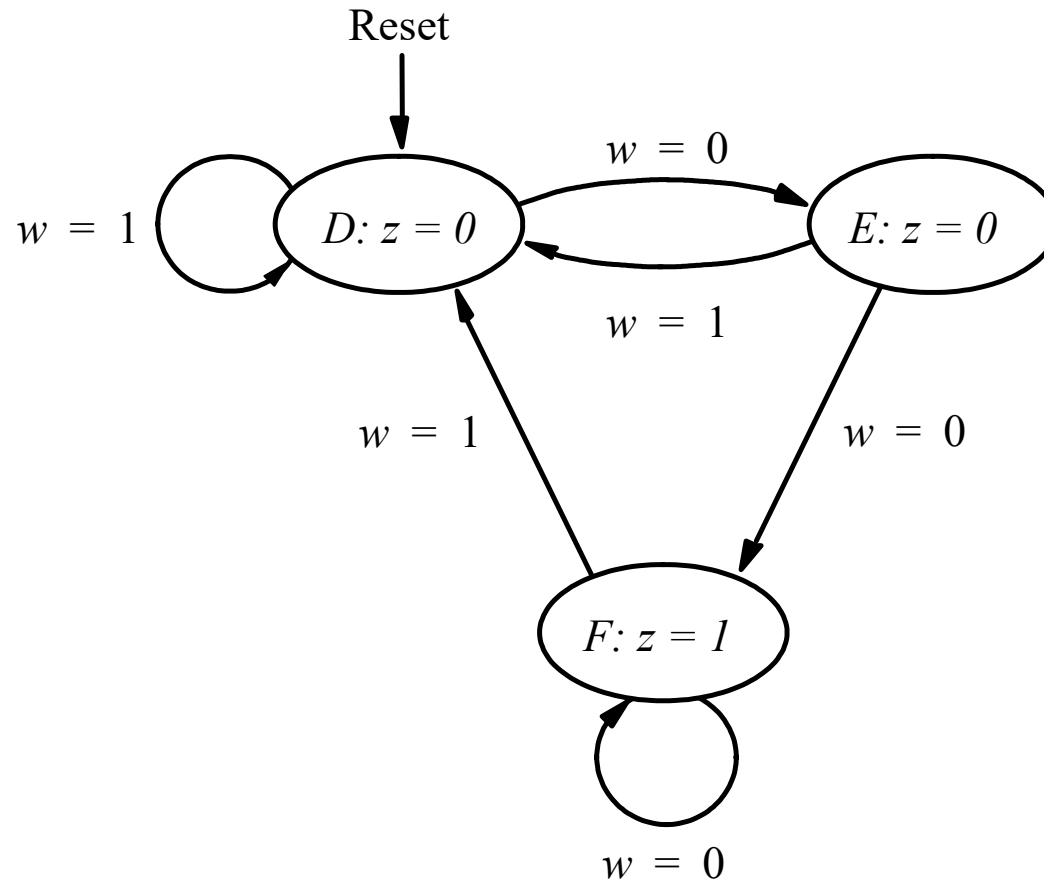
This is similar to the previous one. Just invert the w's and relabel the states to D,E,F.
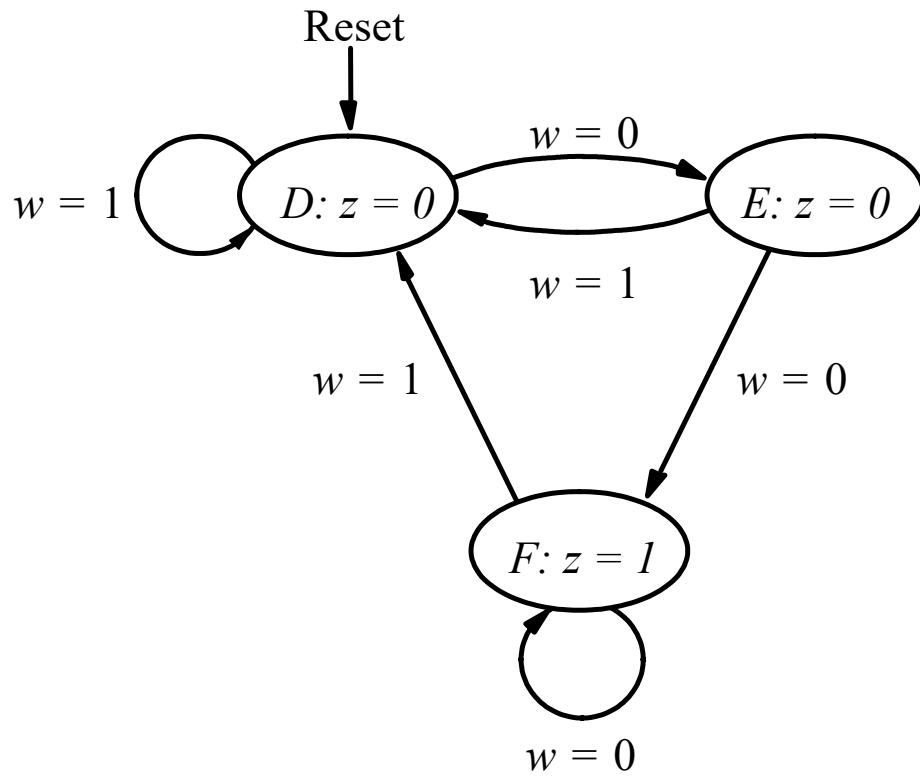
Present state	Next state		Output z
	$w = 0$	$w = 1$	
D E F			

Present state	Next state		Output z
	$w = 0$	$w = 1$	
D	E	D	0
E	F	D	0
F	F	D	1

FSM that detects a sequence of two zeros

Present state	Next state		Output
	$w = 0$	$w = 1$	z_{zeros}
D	E	D	0
E	F	D	0
F	F	D	1

(a) State table

Present state		Next state		Output
		$w = 0$	$w = 1$	
	$y_4 y_3$	$Y_4 Y_3$	$Y_4 Y_3$	z_{zeros}
D	00	01	00	0
E	01	11	00	0
F	11	11	00	1
	10	dd	dd	d

[Figure 6.90 from the textbook]

FSM that detects a sequence of two zeros

Present state	Ne xt state		Output z_{zeros}
	$w = 0$	$w = 1$	
D	E	D	0
E	F	D	0
F	F	D	1

(a) State table

Only these two columns are swapped relative to the first FSM. And the states have different names now.

Present state	Next state		Output z_{zeros}
$y_4 y_3$	$w = 0$ $Y_4 Y_3$	$w = 1$ $Y_4 Y_3$	
D 00	01	00	0
E 01	11	00	0
F 11	11	00	1
10	dd	dd	d

Only these two columns are swapped relative to the first FSM.

[Figure 6.90 from the textbook]

Let's Derive the Logic Expressions

Present state	Next state		Output
	$w = 0$	$w = 1$	z
$y_4 y_3$	$Y_4 Y_3$	$Y_4 Y_3$	
D 00	01	00	0
E 01	11	00	0
F 11	11	00	1
10	dd	dd	d

[Figure 6.90 from the textbook]

Let's Derive the Logic Expressions

	Present state	Next state		Output
		$w = 0$	$w = 1$	z
	$y_4 y_3$	$Y_4 Y_3$	$Y_4 Y_3$	
D	00	01	00	0
E	01	11	00	0
F	11	11	00	1
	10	dd	dd	d

Y_4

$y_4 y_3$

w

	00	01	11	10
0				
1				

Y_3

$y_4 y_3$

w

	00	01	11	10
0				
1				

z

y_4

y_3

	0	1
0		
1		

Let's Derive the Logic Expressions

Present state	Next state		Output
	$w = 0$	$w = 1$	z
y_4y_3	$Y_4\,Y_3$	$Y_4\,Y_3$	
D 00	01	00	0
E 01	11	00	0
F 11	11	00	1
10	dd	dd	d

Y_4 y_4y_3

w	00	01	11	10
0	0	1	1	d
1	0	0	0	d

$$Y_4(w, y_4, y_3) = \overline{w}\,y_3$$

Y_3 y_4y_3

w	00	01	11	10
0	1	1	1	d
1	0	0	0	d

$$Y_3(w, y_4, y_3) = \overline{w}$$

z y_3

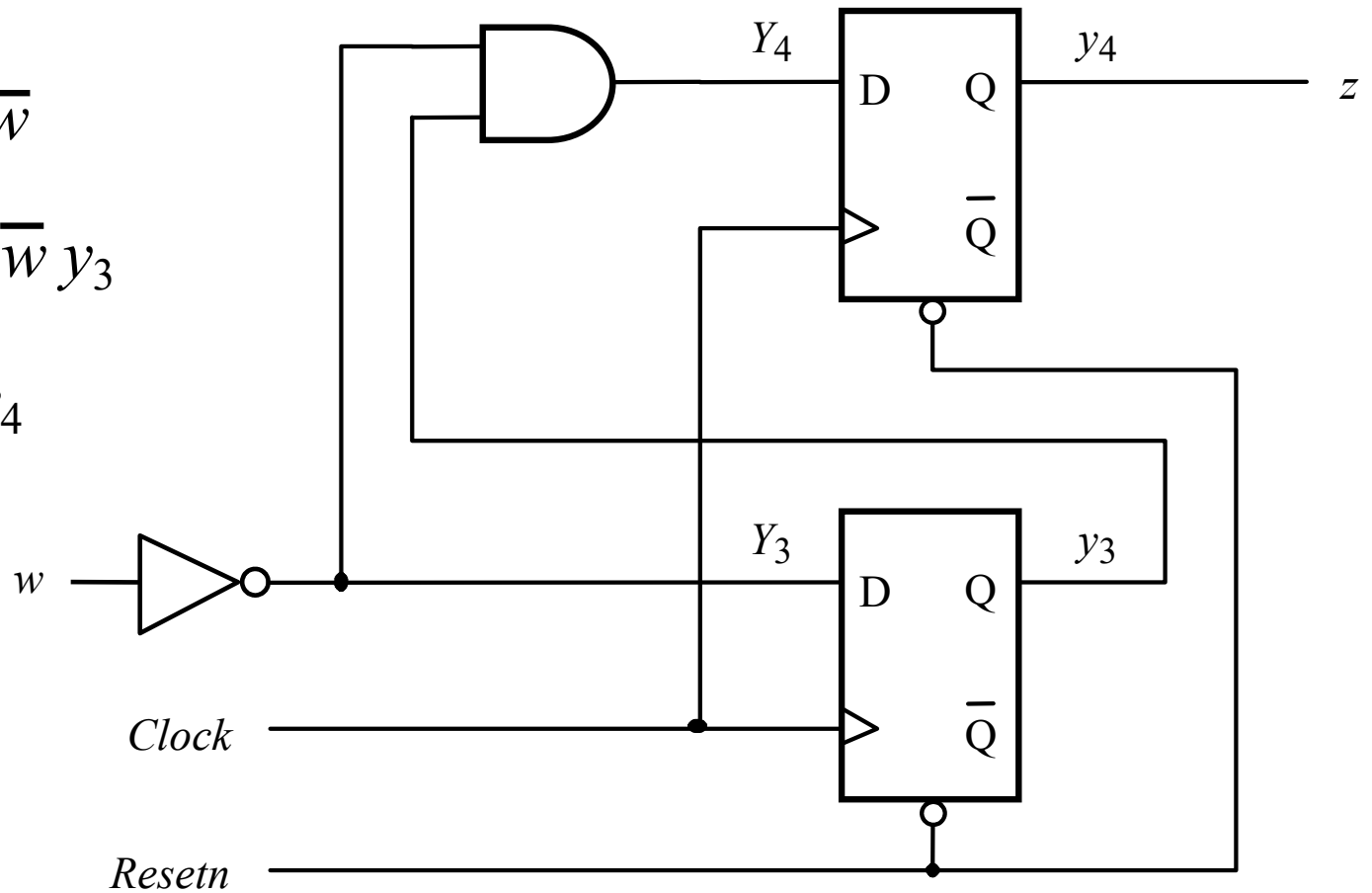| y_4	0	1
0	0	0
1	d	1

$$z(y_4, y_3) = y_4$$

The Circuit Diagram

$Y_3(w, y_4, y_3) = \overline{w}$

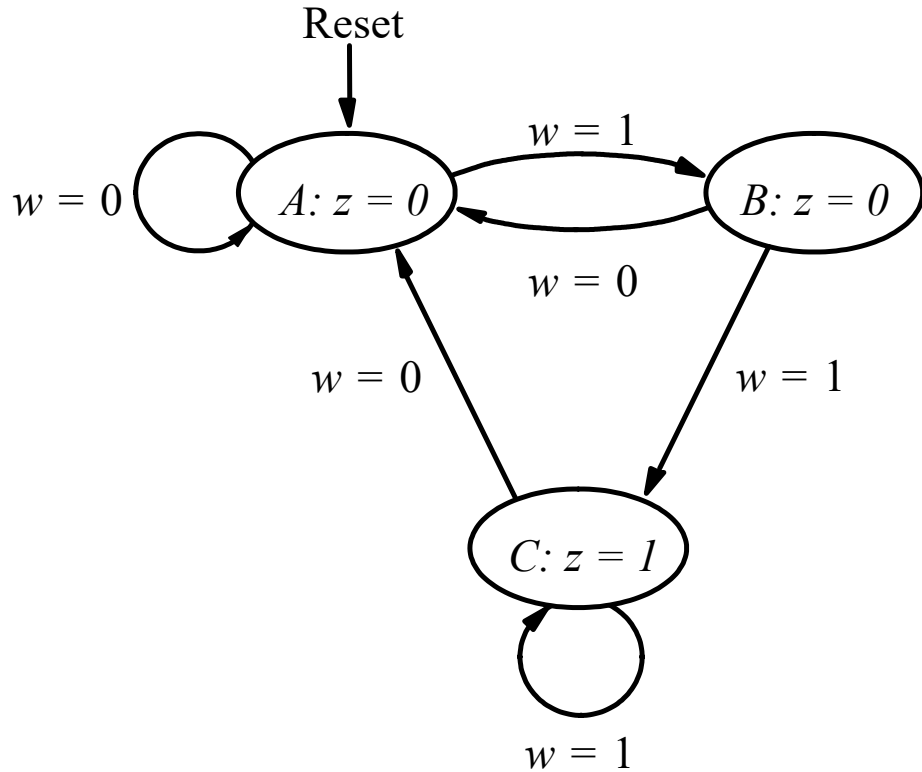$Y_4(w, y_4, y_3) = \overline{w}\, y_3$
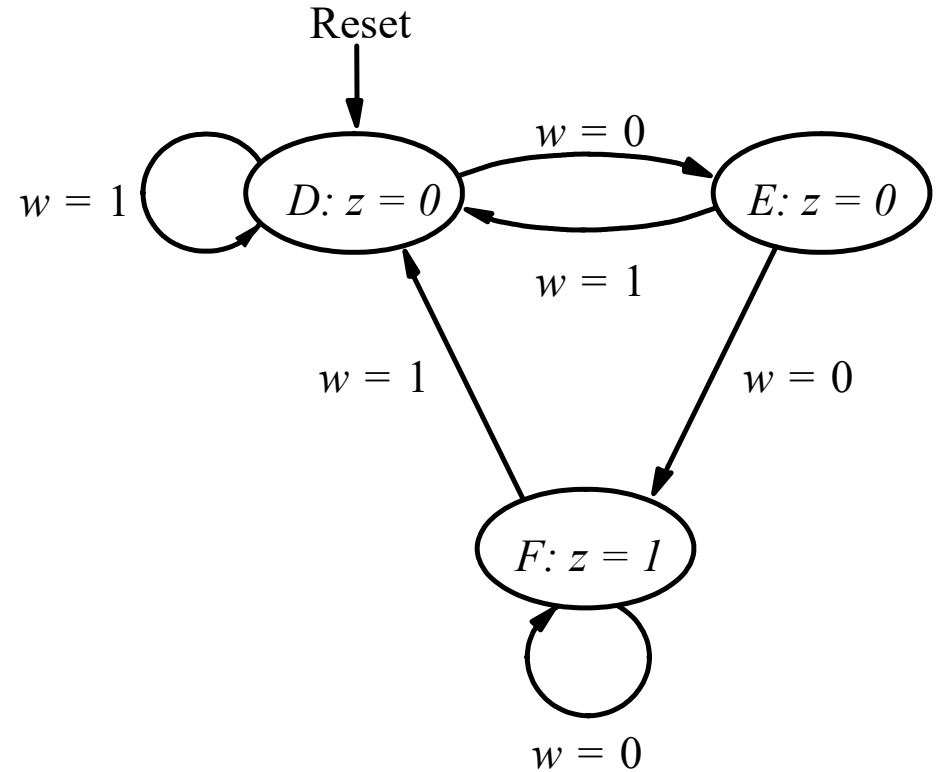
$z(y_2, y_1) = y_4$

Example 6.13

(Combine the two FSMs)

The Two FSMs
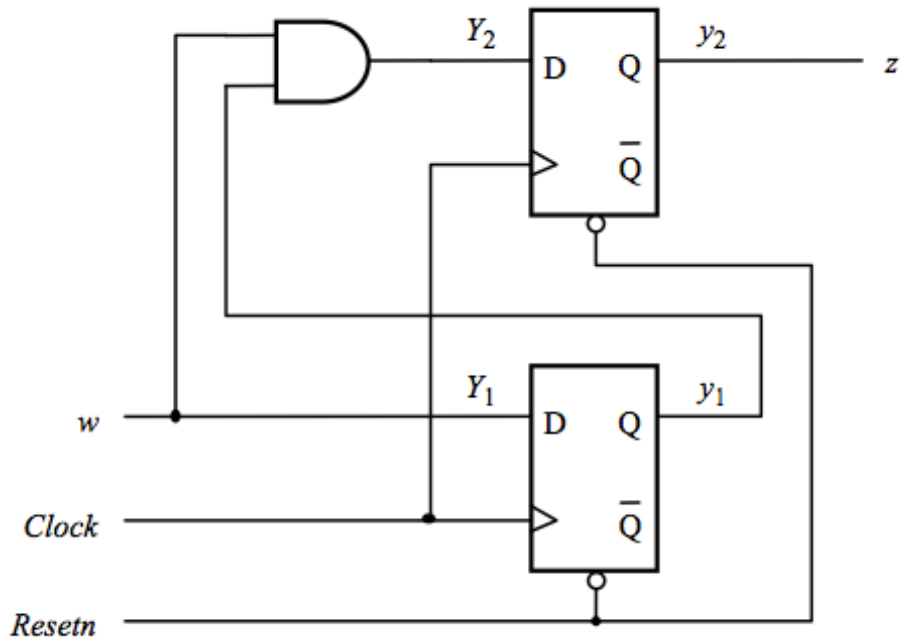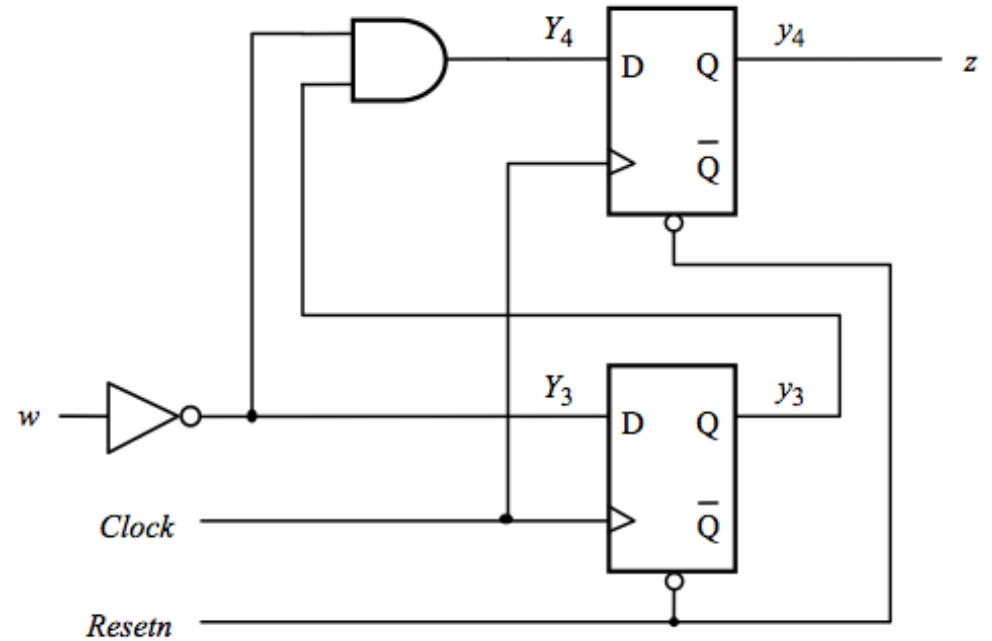

Detect two consecutive 1's   Detect two consecutive 0's

The Two Circuit Diagrams

Detect two consecutive 1's   Detect two consecutive 0's

The Combined Circuit Diagram
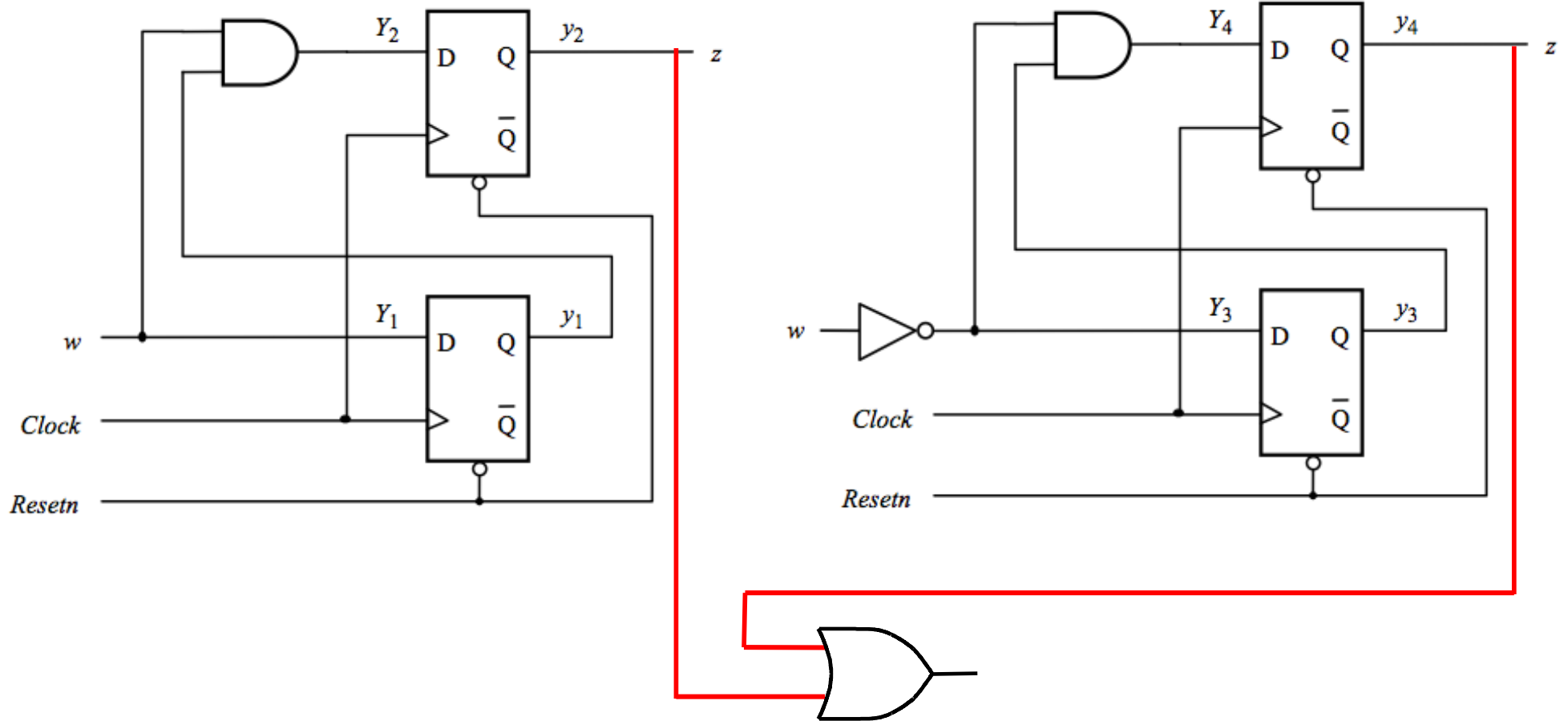
Detect two consecutive 1's or two consecutive 0's

Example 6.14

Goal

- **Design an FSM that detects if the previous two values of the input w were equal to 00 or 11.**

- **If either condition is true then the output z should be set to 1; otherwise to 0.**

- **Implement this as a Mealy-type machine**

State Diagram

[Figure 6.91 from the textbook]
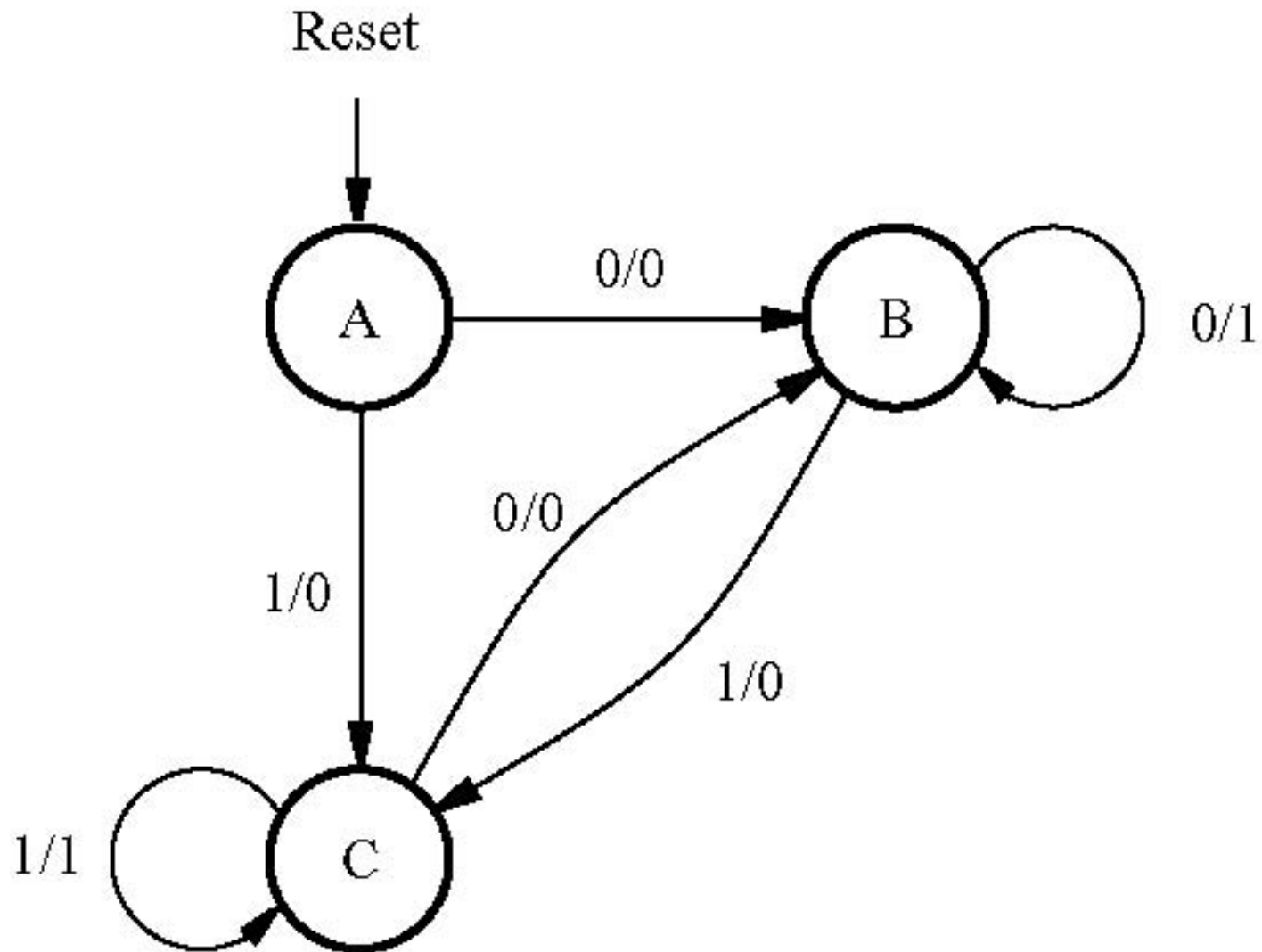
Building the State Table
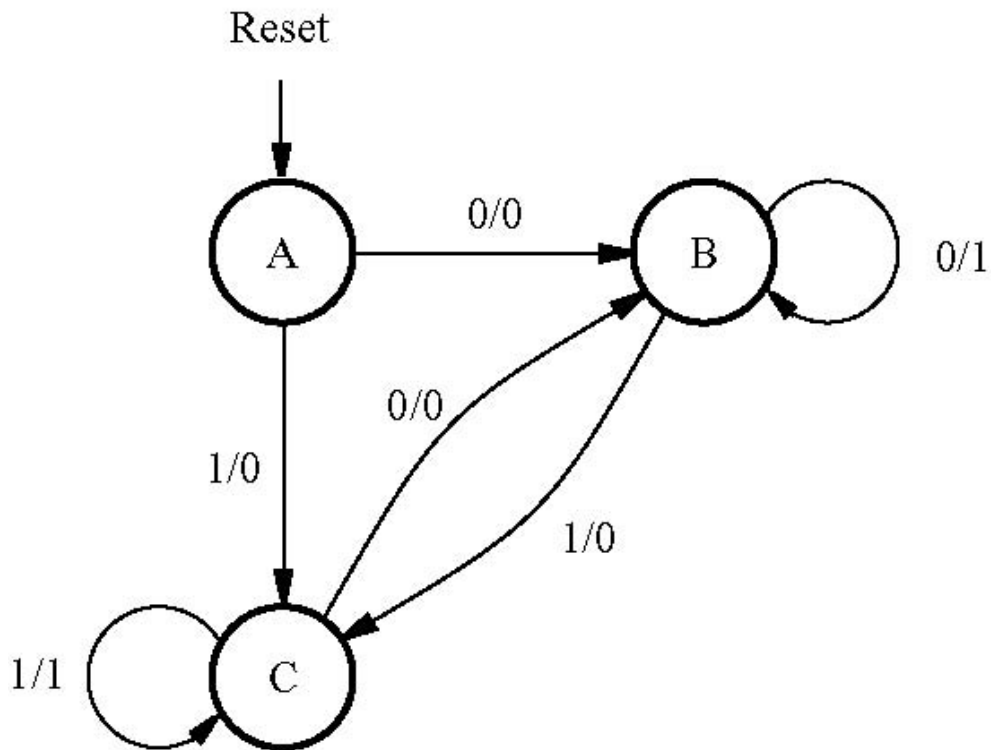
Present state	Next state		Output z	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
A	B	C	0	0
B	B	C	1	0
C	B	C	0	1

State Table

Present state	Next state		Output z	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
A	B	C	0	0
B	B	C	1	0
C	B	C	0	1

[Figure 6.92 from the textbook]

Building the State-Assigned Table

Present state	Next state		Output z	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
A	B	C	0	0
B	B	C	1	0
C	B	C	0	1

	Present state	Next state		Output	
		$w = 0$	$w = 1$	$w = 0$	$w = 1$
	$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	z	z
A	00	01	11	0	0
B	01	01	11	1	0
C	11	01	11	0	1

[Figure 6.93 from the textbook]

State-Assigned Table

Present state	Next state		Output	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
y_2y_1	Y_2Y_1	Y_2Y_1	z	z
A 00	01	11	0	0
B 01	01	11	1	0
C 11	01	11	0	1

State-Assigned Table

Present state	Next state		Output	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	z	z
A 00	01	11	0	0
B 01	01	11	1	0
C 11	01	11	0	1

cut here

State-Assigned Table

	Present state	Next state		Output	
		$w = 0$	$w = 1$	$w = 0$	$w = 1$
	$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	z	z
A	00	01	11	0	0
B	01	01	11	1	0
C	11	01	11	0	1

State-Assigned Table

	Present state	Next state		Output	
		$w = 0$	$w = 1$	$w = 0$	$w = 1$
	$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	z	z
A	00	01	11	0	0
B	01	01	11	1	0
	1 0	d d	d d	d	d
C	11	01	11	0	1

Truth Table for Y_2, Y_1, and z

Present state	Next state		Output	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	z	z
A 00	01	11	0	0
B 01	01	11	1	0
10	d d	d d	d	d
C 11	01	11	0	1

w	y_2	y_1	Y_2	Y_1	z
0	0	0	0	1	0
0	0	1	0	1	1
0	1	0	d	d	d
0	1	1	0	1	0
1	0	0	1	1	0
1	0	1	1	1	0
1	1	0	d	1	d
1	1	1	1	1	1

K-Maps for Y_2, Y_1, and z

Y_2

$w\, y_2$ / y_1

	00	01	11	10
0	0	d	d	1
1	0	0	1	1

Y_1

$w\, y_2$ / y_1

	00	01	11	10
0	1	d	1	1
1	1	1	1	1

z

$w\, y_2$ / y_1

	00	01	11	10
0	0	d	d	0
1	1	0	1	0

w	y_2	y_1	Y_2	Y_1	z
0	0	0	0	1	0
0	0	1	0	1	1
0	1	0	d	d	d
0	1	1	0	1	0
1	0	0	1	1	0
1	0	1	1	1	0
1	1	0	d	1	d
1	1	1	1	1	1

K-Maps for Y_2, Y_1, and z

Y_2

$w\, y_2$

y_1

	00	01	11	10
0	0	d	d	1
1	0	0	1	1

$Y_2 = w$

Y_1

$w\, y_2$

y_1

	00	01	11	10
0	1	d	1	1
1	1	1	1	1

$Y_1 = 1$

z

$w\, y_2$

y_1

	00	01	11	10
0	0	d	d	0
1	1	0	1	0

$z = \overline{w}\, y_1\, \overline{y_2} + w\, y_2$

w	y_2	y_1	Y_2	Y_1	z
0	0	0	0	1	0
0	0	1	0	1	1
0	1	0	d	d	d
0	1	1	0	1	0
1	0	0	1	1	0
1	0	1	1	1	0
1	1	0	d	1	d
1	1	1	1	1	1

State-Assigned Table

Present state	Next state		Output	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
y_2y_1	Y_2Y_1	Y_2Y_1	z	z
A 00	01	11	0	0
B 01	01	11	1	0
C 11	01	11	0	1

$Y_1 = 1$

$Y_2 = w$

$z = \overline{w} \, y_1 \, \overline{y_2} + w \, y_2$

State-Assigned Table

Present state	Next state		Output	
	$w = 0$	$w = 1$	$w = 0$	$w = 1$
$y_2 y_1$	$Y_2 Y_1$	$Y_2 Y_1$	z	z
A 00	01	11	0	0
B 01	01	11	1	0
C 11	01	11	0	1

$$Y_1 = 1$$
$$Y_2 = w$$
$$z = \overline{w}\, y_1\, \overline{y}_2 + w\, y_2$$

The Circuit Diagram

The Circuit Diagram
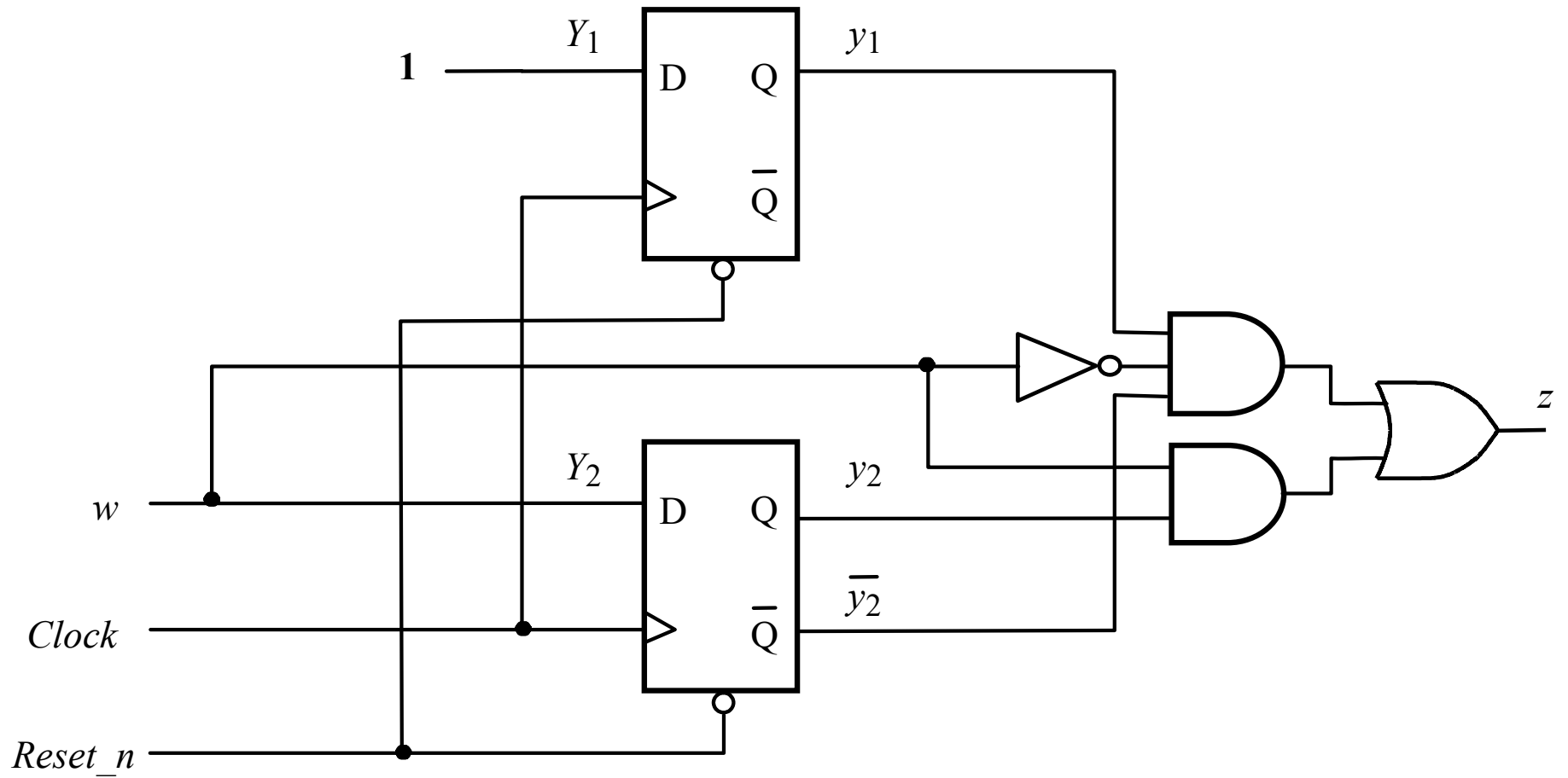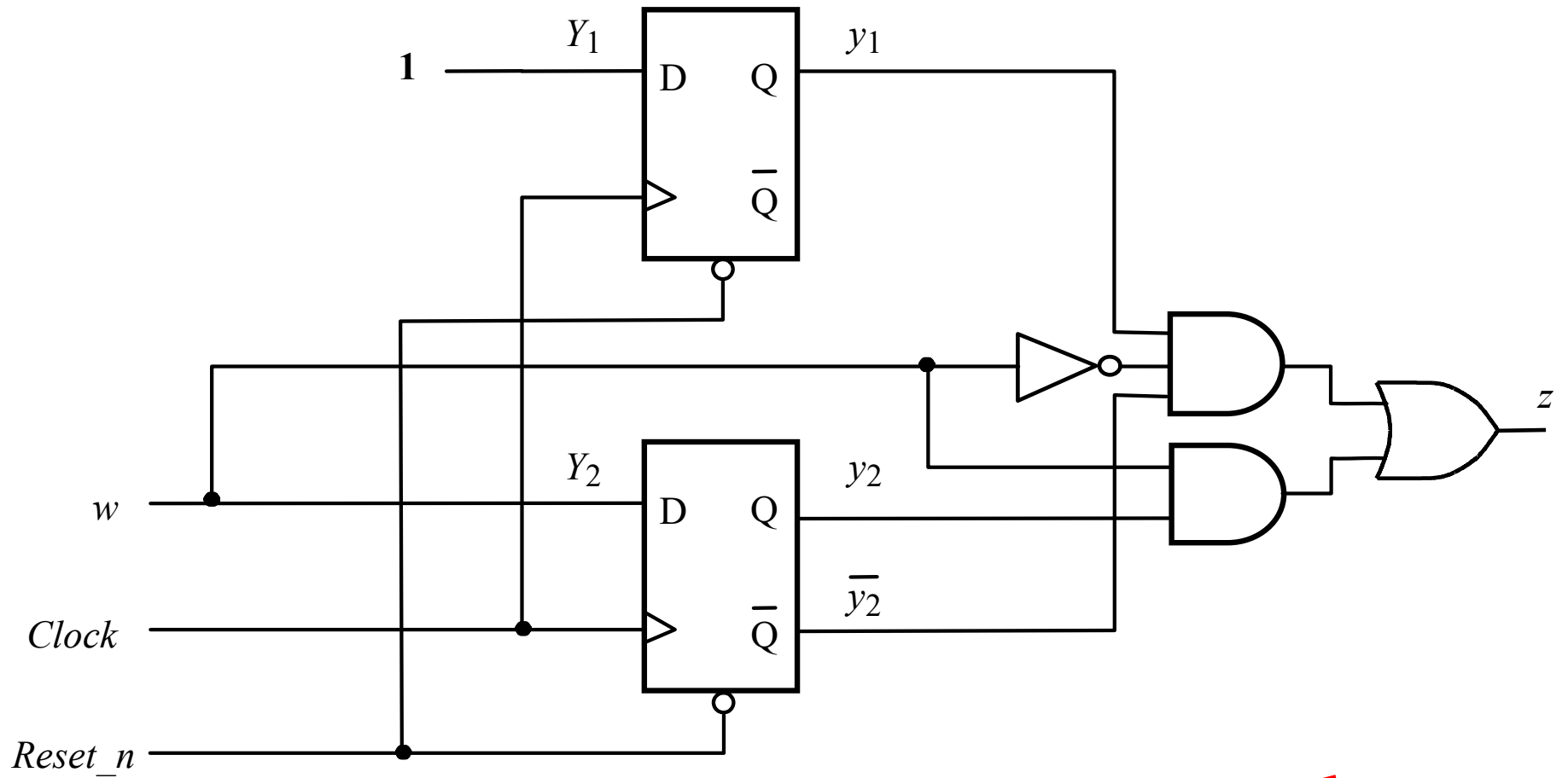
$$Y_1 = 1$$
$$Y_2 = w$$
$$z = \overline{w}\, y_1\, \overline{y}_2 + w\, y_2$$

The Circuit Diagram

$Y_1 = 1$

$Y_2 = w$
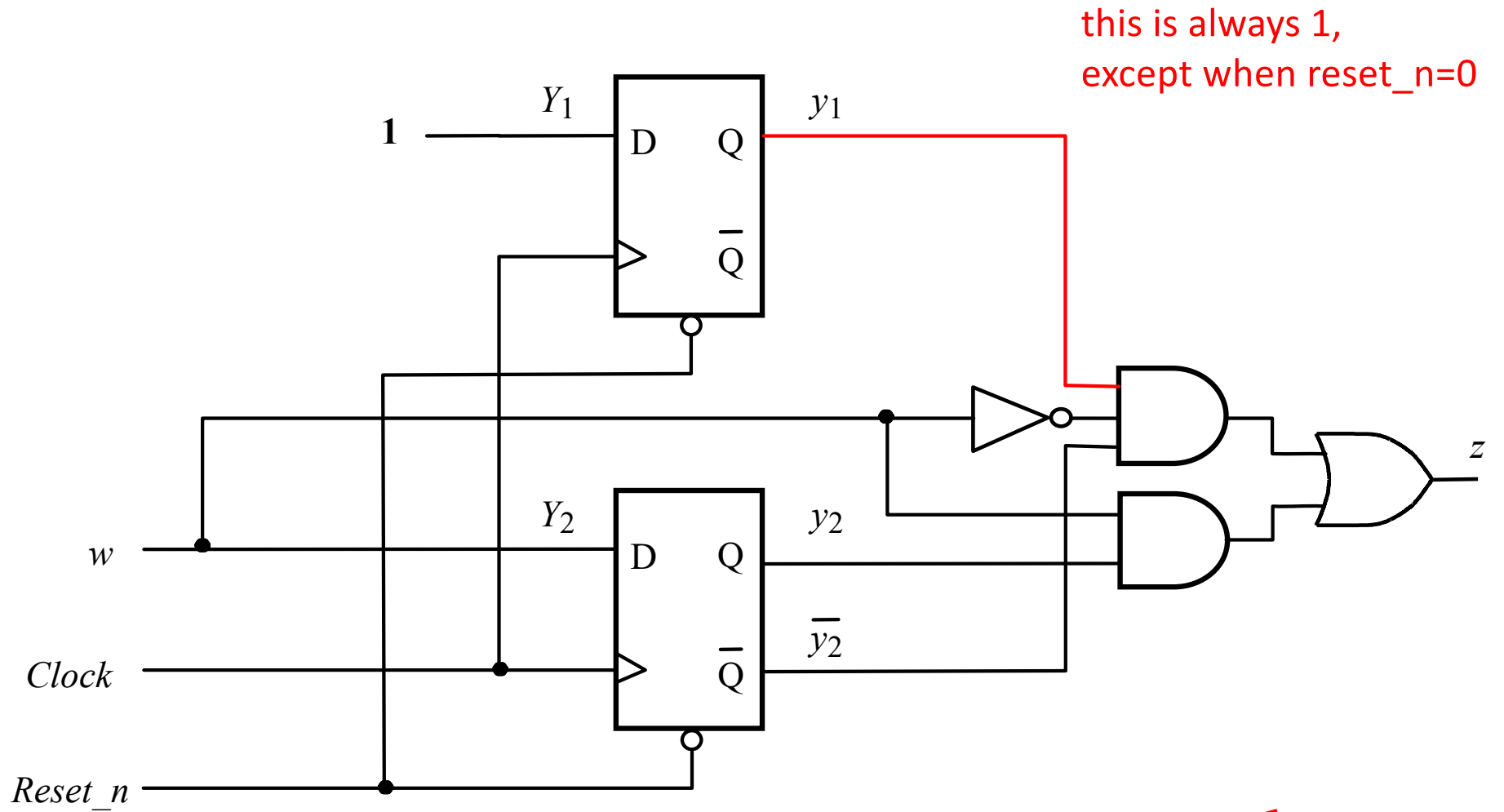
$z = \overline{w}\,\overline{y_1}\,\overline{y_2} + w\,y_2$

The Circuit Diagram

The Simplified Circuit Diagram

$$Y_2 = w$$
$$z = \overline{w}\ \overline{y_2} + w\ y_2$$

Original State Diagram

[Figure 6.91 from the textbook]
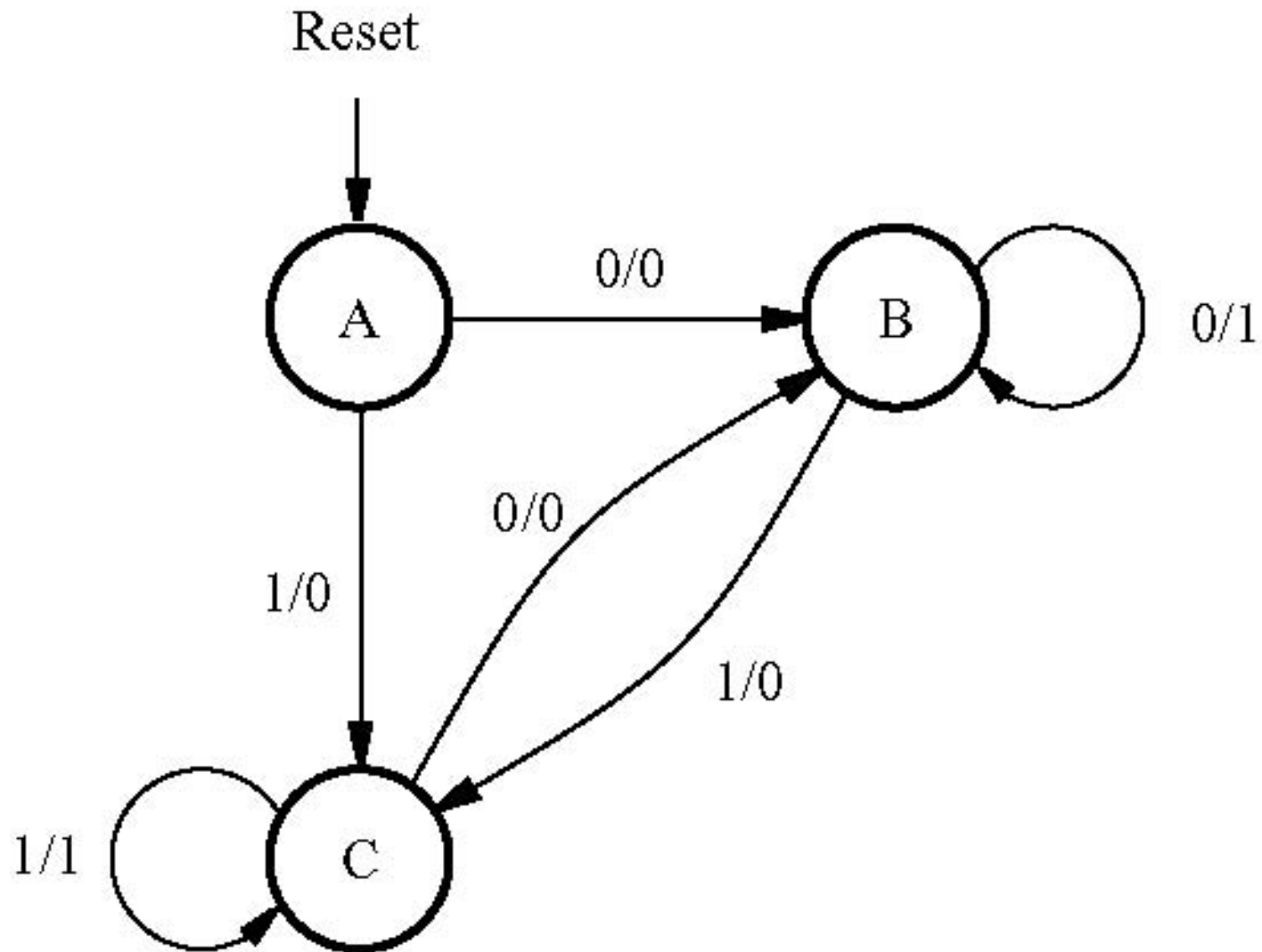
New State Diagram
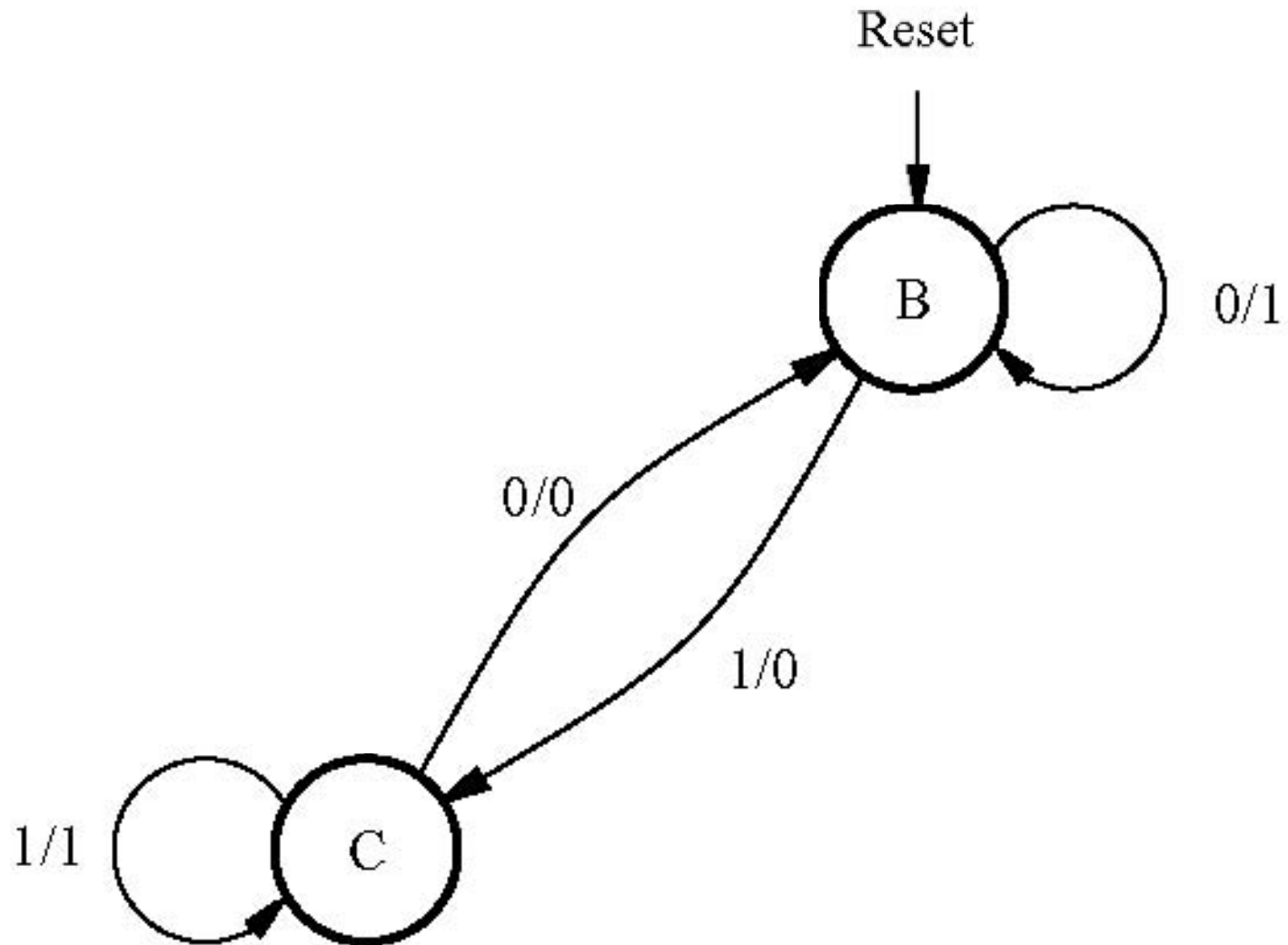
Example 6.15

Goal

Implement this state-assigned Table using JK flip-flops

	Present state $y_3 y_2 y_1$	Next state $w = 0$ $Y_3 Y_2 Y_1$	Next state $w = 1$ $Y_3 Y_2 Y_1$	Output z
A	000	100	110	0
B	100	101	110	0
C	101	101	110	1
D	110	100	111	0
E	111	100	111	1

Excitation table with JK flip-flops

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

$Q(t) \rightarrow Q(t+1)$	J K
$0 \rightarrow 0$	0 d
$0 \rightarrow 1$	1 d
$1 \rightarrow 0$	d 1
$1 \rightarrow 1$	d 0

[Figure 6.94 from the textbook]

Excitation table with JK flip-flops

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A	000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B	100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C	101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D	110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E	111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

Q(t) → Q(t+1)	J K
0 → 0	0 d
0 → 1	1 d
1 → 0	d 1
1 → 1	d 0

Excitation table with JK flip-flops

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

Q(t) → Q(t+1)	J K
0 → 0	0 d
0 → 1	1 d
1 → 0	d 1
1 → 1	d 0

Excitation table with JK flip-flops

Present state $y_3y_2y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

Q(t) → Q(t+1)	J K
0 → 0	0 d
0 → 1	1 d
1 → 0	d 1
1 → 1	d 0

Excitation table with JK flip-flops

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

Q(t) → Q(t+1)	J K
0 → 0	0 d
0 → 1	1 d
1 → 0	d 1
1 → 1	d 0

Excitation table with JK flip-flops

Present state $y_3 y_2 y_1$	$w = 0$					$w = 1$				Output z
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$		$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$		110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$		110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$		110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$		111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$		111	$d0$	$d0$	$d0$	1

$Q(t) \rightarrow Q(t+1)$	J K
$0 \rightarrow 0$	0 d
$0 \rightarrow 1$	1 d
$1 \rightarrow 0$	d 1
$1 \rightarrow 1$	d 0

Excitation table with JK flip-flops

Present state $y_3 y_2 y_1$	$w = 0$					$w = 1$				Output z
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$		$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A	000	100	$1d$	$0d$	$0d$		110	$1d$	$1d$	$0d$	0
B	100	101	$d0$	$0d$	$1d$		110	$d0$	$1d$	$0d$	0
C	101	101	$d0$	$0d$	$d0$		110	$d0$	$1d$	$d1$	1
D	110	100	$d0$	$d1$	$0d$		111	$d0$	$d0$	$1d$	0
E	111	100	$d0$	$d1$	$d1$		111	$d0$	$d0$	$d0$	1

The column header row spans "Flip-flop inputs" over the $w=0$ and $w=1$ groups.

$Q(t) \rightarrow Q(t+1)$	J	K
$0 \rightarrow 0$	0	d
$0 \rightarrow 1$	1	d
$1 \rightarrow 0$	d	1
$1 \rightarrow 1$	d	0

Excitation table with JK flip-flops

Present state $y_3y_2y_1$	Flip-flop inputs								Output z
	$w=0$				$w=1$				
	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

Q(t) → Q(t+1)	J K
0 → 0	0 d
0 → 1	1 d
1 → 0	d 1
1 → 1	d 0

And so on...

The Expression for z

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

z is equal to y_1

The Expression for J_3

Present state $y_3y_2y_1$	Flip-flop inputs								Output z
		$w = 0$				$w = 1$			
	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	
A 000	100	1d	0d	0d	110	1d	1d	0d	0
B 100	101	d0	0d	1d	110	d0	1d	0d	0
C 101	101	d0	0d	d0	110	d0	1d	d1	1
D 110	100	d0	d1	0d	111	d0	d0	1d	0
E 111	100	d0	d1	d1	111	d0	d0	d0	1

J_3 is equal to 1

The Expression for K₃

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	1d	0d	0d	110	1d	1d	0d	0
B 100	101	d0	0d	1d	110	d0	1d	0d	0
C 101	101	d0	0d	d0	110	d0	1d	d1	1
D 110	100	d0	d1	0d	111	d0	d0	1d	0
E 111	100	d0	d1	d1	111	d0	d0	d0	1

K_3 is equal to 0

The Expression for J_2

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

J_2 is equal to w

The Expression for K₂

Present state $y_3y_2y_1$	Flip-flop inputs								Output z
		$w=0$				$w=1$			
	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	$Y_3Y_2Y_1$	J_3K_3	J_2K_2	J_1K_1	
A 000	100	1d	0d	0d	110	1d	1d	0d	0
B 100	101	d0	0d	1d	110	d0	1d	0d	0
C 101	101	d0	0d	d0	110	d0	1d	d1	1
D 110	100	d0	d1	0d	111	d0	d0	1d	0
E 111	100	d0	d1	d1	111	d0	d0	d0	1

K_2 is equal to $\overline{w}$

The Expression for J_1

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
		$w = 0$				$w = 1$			
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

J_1 is equal to $w\, y_2 + \overline{w}\, y_3\, \overline{y_2}$

The Expression for K₁

Present state $y_3 y_2 y_1$	Flip-flop inputs								Output z
	$w = 0$				$w = 1$				
	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	$Y_3 Y_2 Y_1$	$J_3 K_3$	$J_2 K_2$	$J_1 K_1$	
A 000	100	$1d$	$0d$	$0d$	110	$1d$	$1d$	$0d$	0
B 100	101	$d0$	$0d$	$1d$	110	$d0$	$1d$	$0d$	0
C 101	101	$d0$	$0d$	$d0$	110	$d0$	$1d$	$d1$	1
D 110	100	$d0$	$d1$	$0d$	111	$d0$	$d0$	$1d$	0
E 111	100	$d0$	$d1$	$d1$	111	$d0$	$d0$	$d0$	1

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K_1 is equal to $\overline{w}\, y_2 + w\, \overline{y_2}\, y_1$

All Logic Expressions

$$J_1 = wy_2 + \overline{w}y_3\overline{y_2}$$

$$K_1 = \overline{w}y_2 + wy_1\overline{y_2}$$

$$J_2 = w$$

$$K_2 = \overline{w}$$

$$J_3 = 1$$

$$K_3 = 0$$

$$z = y_1$$

Questions?

THE END